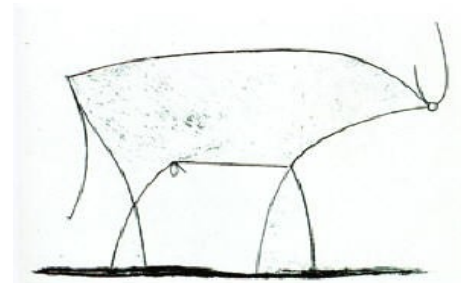
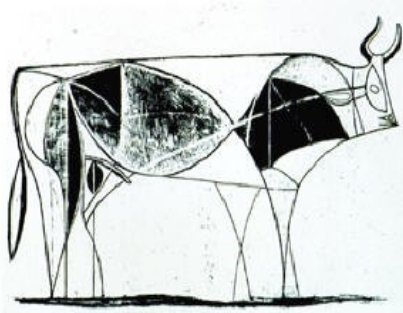
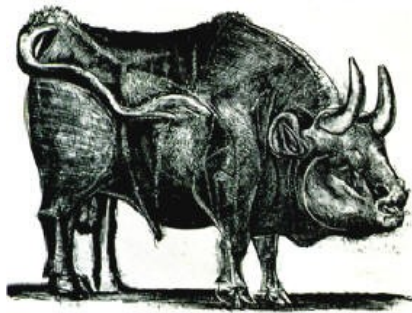


Advanced Statistics for better Cosmological Inference

Amir Aghamousa

Asia Pacific Center for Theoretical Physics, Pohang, South Korea

IBS-KASI Joint Workshop, August 19~20, 2015



Bull pictures courtesy of "Pablo Picasso"

All models are false, some are useful. (George E. P. Box)

I will talk about:

- Strong Lens Time Delay Challenge II (with Arman Shafieloo)
- Time delay estimation of SDSS J1001+5027 (with Arman Shafieloo)
- Supernova Type Ia classification (with Arman Shafieloo, Alex G. Kim)

If I have time,

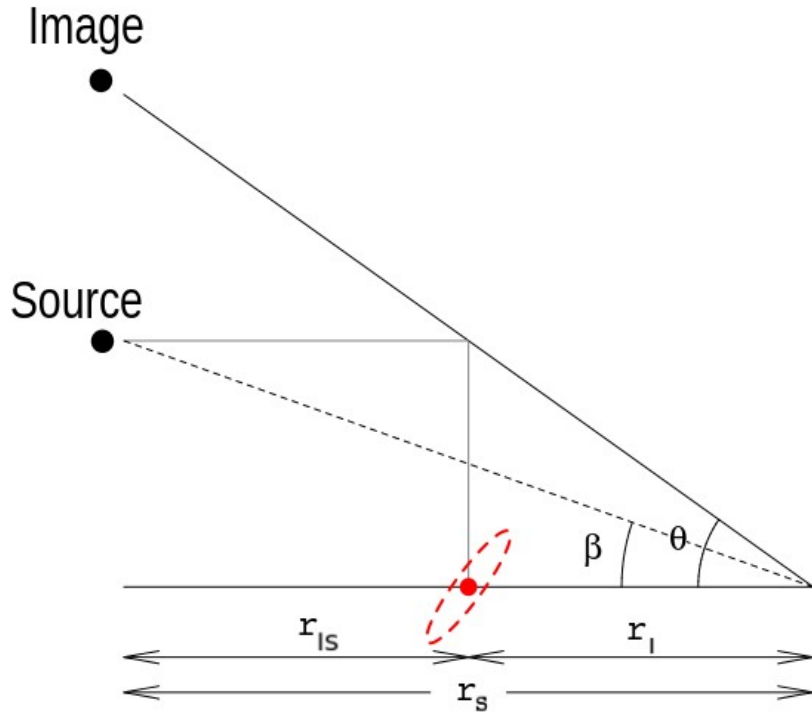


talk about:

- Model-independent estimation of CMB angular power spectrum (with Arman Shafieloo, Mihir Arjunwadkar, Tarun Souradeep)
- Nonparametric test of consistency between cosmological models and CMB data (with Arman Shafieloo)

Strong Lens Time Delay Challenge II

Strong gravitational lensing



HST ACS image of RXJ1131-1231

Time delay:
$$\Delta t(\vec{\theta}, \vec{\beta}) = \frac{r_l r_s}{r_{ls}} (1 + z_l) \phi(\vec{\theta}, \vec{\beta})$$

Fermat potential:
$$\phi(\vec{\theta}, \vec{\beta}) = \frac{(\vec{\theta} - \vec{\beta})^2}{2} - \psi(\vec{\theta})$$

lensing potential delay
geometric delay

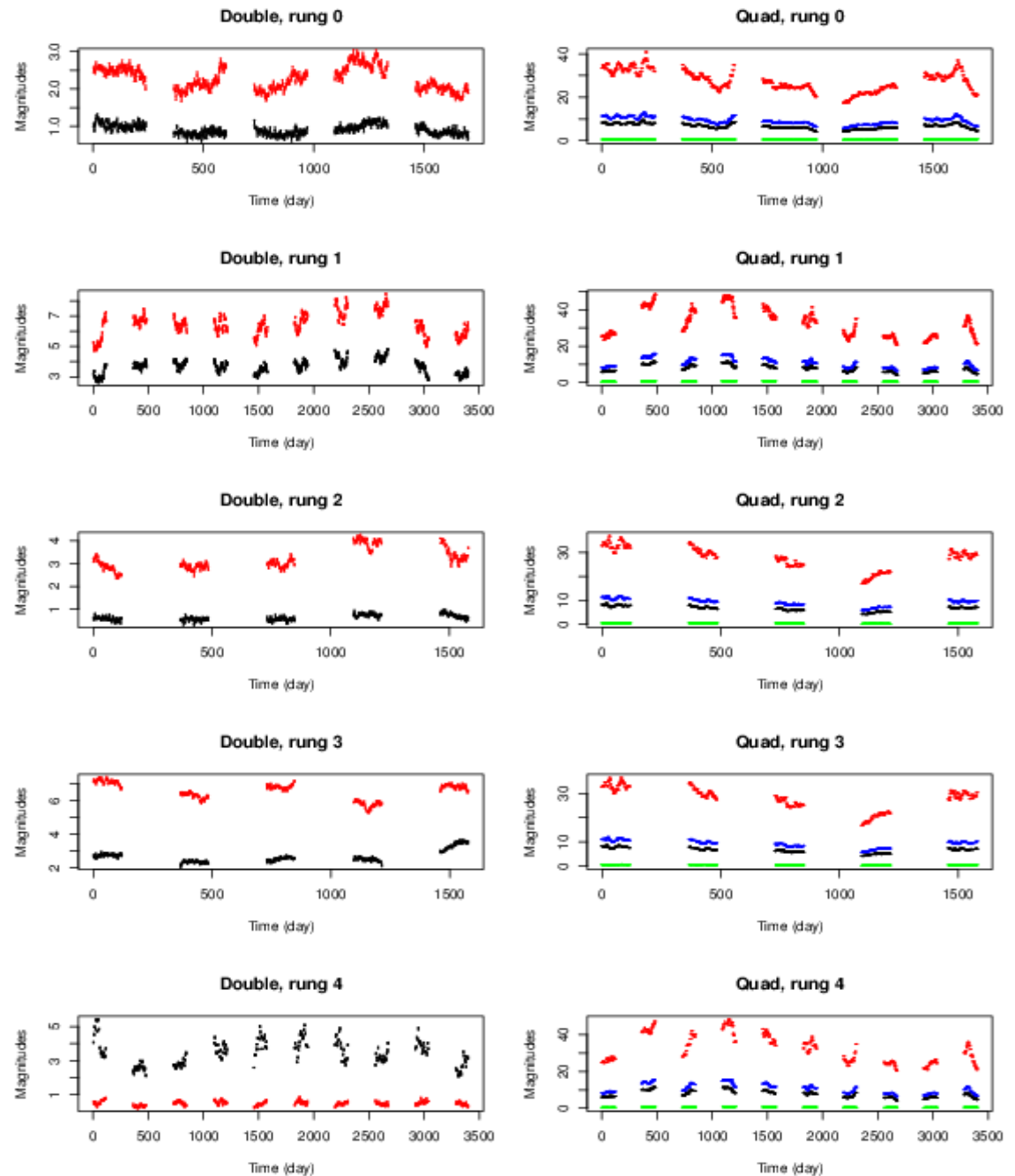
Strong lensing surveys

- ☀ Recent survey:
COSMOGRAIL: the COSmological MOnitoring of GRAVItational Lenses
(<http://www.cosmograil.org>)
- ☀ Future survey:
LSST: the Large Synoptic Survey Telescope (LSST) with 10 years observation
will be expected to monitor several thousand time delay lens systems.
- ☀ Need to design the fast and reliable algorithms for the time delay estimation.
- ☀ Strong Lens Time Delay Challenge:
TDC0
TDC1

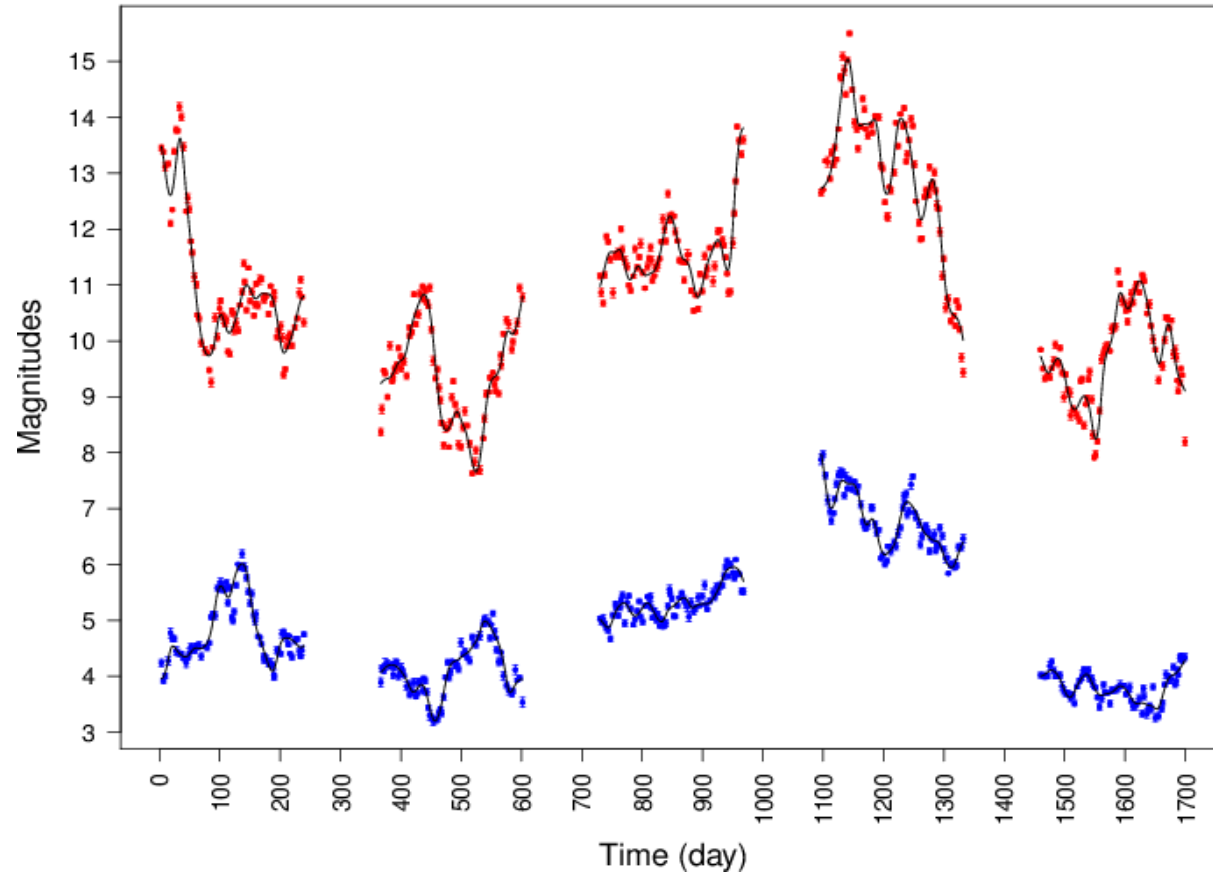
Strong Lens Time Delay Challenge: simulated data

The TDC1 simulated data is provided in five different categories (rungs)

Each rung contains the light curves of 720 Double and 152 Quad image systems.



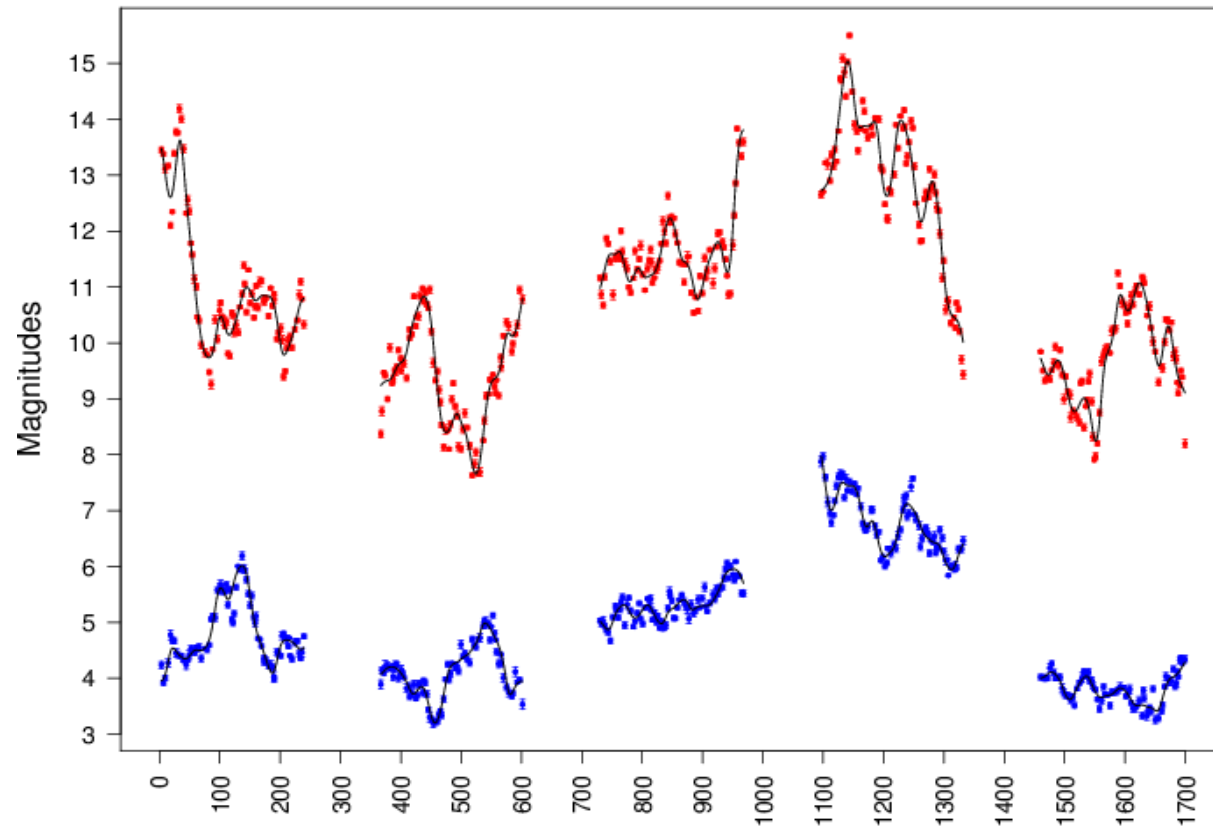
Methodology: smoothing



$$A^s(t) = A^g(t) + N(t) \sum_i \frac{A^d(t_i) - A^g(t_i)}{\sigma_d^2(t_i)} \times \exp \left[-\frac{(t_i - t)^2}{2\Delta^2} \right]$$

$$\text{where } N(t)^{-1} = \sum_i \exp \left[-\frac{(t_i - t)^2}{2\Delta^2} \right] \frac{1}{\sigma_d^2(t_i)}$$

Methodology: cross-correlation



$$\rho_{XY} = \frac{\text{cov}(X, Y)}{\sigma_X \sigma_Y} \longrightarrow r_{xy} = \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sqrt{\sum_{i=1}^n (x_i - \bar{x})^2 \sum_{i=1}^n (y_i - \bar{y})^2}},$$

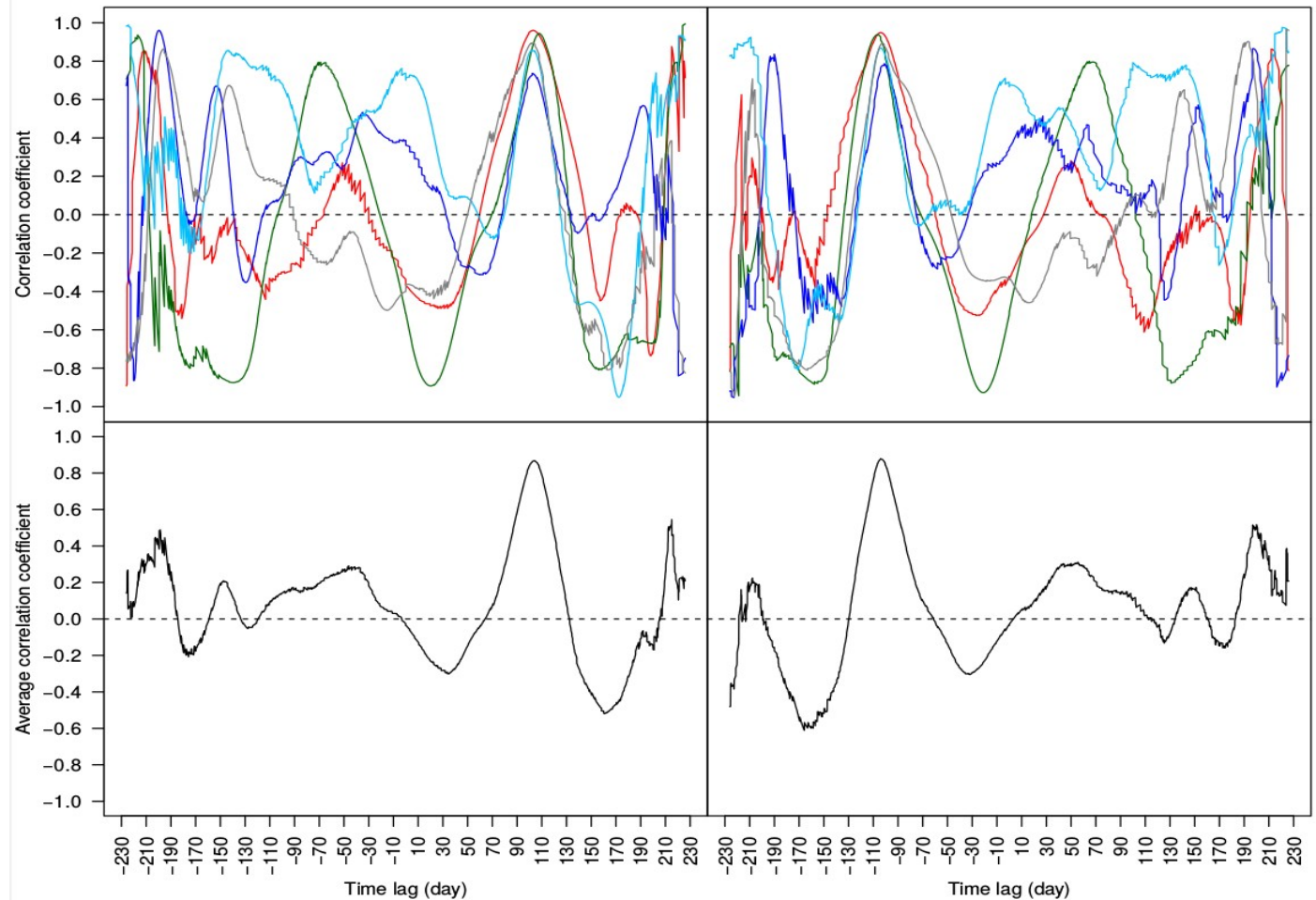
Microlensing

~~Worries~~

$$\left. \begin{aligned} X' &= a_x X + b_x \\ Y' &= a_y Y + b_y \end{aligned} \right\} \longrightarrow \rho_{XY} = \rho_{X'Y'}$$

(Peterson 2001, Wasserman 2004)

Methodology: time delay estimation



Correlation > 0.6

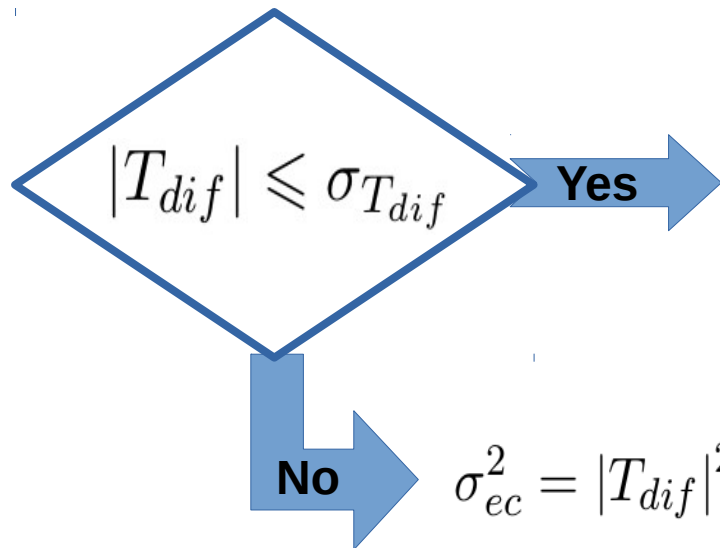


$$|\tilde{\Delta}t_{A_1 A_2}| = \frac{|\tilde{\Delta}t_{A_1; A_2^s}| + |\tilde{\Delta}t_{A_2; A_1^s}|}{2} \quad \sigma_{A_1 A_2}^{ini} = \sqrt{2} \times \frac{\left| |\tilde{\Delta}t_{A_1; A_2^s}| - |\tilde{\Delta}t_{A_2; A_1^s}| \right|}{2}$$

Methodology: error estimation, using Quad systems

The light curves of a Quad image are labeled A1 , A2 , B1 and B2. For every Quad system we should have:

$$\underbrace{\tilde{\Delta}t_{A_1 A_2} - (\tilde{\Delta}t_{A_1 B_1} + \tilde{\Delta}t_{B_1 A_2})}_{T_{dif}} \pm \underbrace{\sqrt{(\sigma_{\tilde{\Delta}t_{A_1 A_2}}^{ini})^2 + (\sigma_{\tilde{\Delta}t_{A_1 B_1}}^{ini})^2 + (\sigma_{\tilde{\Delta}t_{B_1 A_2}}^{ini})^2}}_{\sigma_{T_{dif}}} \equiv 0$$



We can assume that all time delays and their corresponding errors are estimated consistently.

$$\text{No} \rightarrow \sigma_{ec}^2 = |T_{dif}|^2 - \sigma_{T_{dif}}^2 \rightarrow \sigma_{\tilde{\Delta}t_{A_1 A_2}}^{new} = \sqrt{(\sigma_{\tilde{\Delta}t_{A_1 A_2}}^{ini})^2 + \frac{\alpha}{3} \sigma_{ec}^2}$$

Methodology: error estimation, using Quad systems

Error profile for Double systems

For Rung 0,

$$\text{if } |\tilde{\Delta}t| \leq 20 \Rightarrow \sigma_R = 0.06 \times |\tilde{\Delta}t|, \quad \text{if } |\tilde{\Delta}t| > 20 \Rightarrow \sigma_R = 1.2$$

For Rung 1,

$$\text{if } |\tilde{\Delta}t| \leq 20 \Rightarrow \sigma_R = 0.06 \times |\tilde{\Delta}t|, \quad \text{if } |\tilde{\Delta}t| > 20 \Rightarrow \sigma_R = 1.3$$

For Rung 2,

$$\text{if } |\tilde{\Delta}t| \leq 30 \Rightarrow \sigma_R = 0.07 \times |\tilde{\Delta}t|, \quad \text{if } |\tilde{\Delta}t| > 30 \Rightarrow \sigma_R = 1.3$$

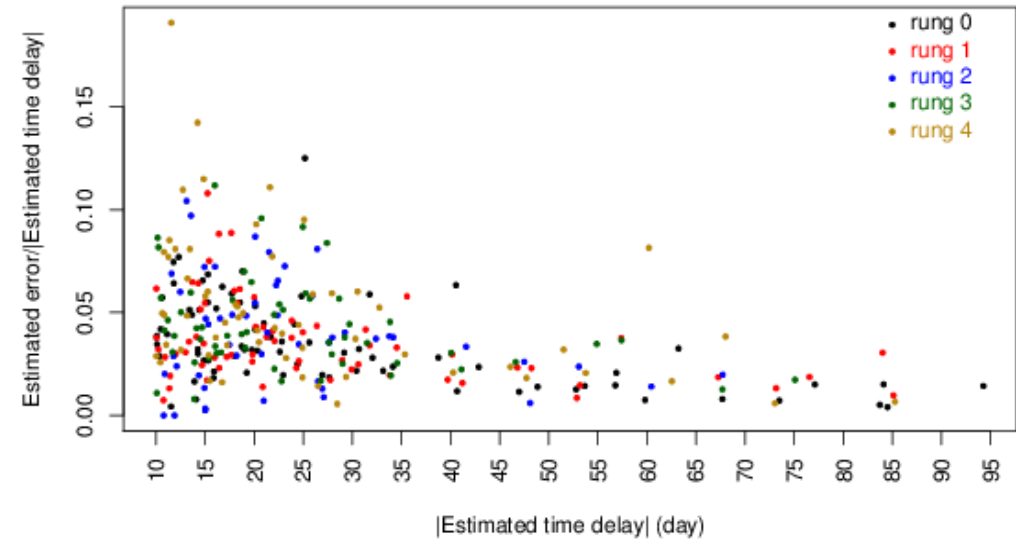
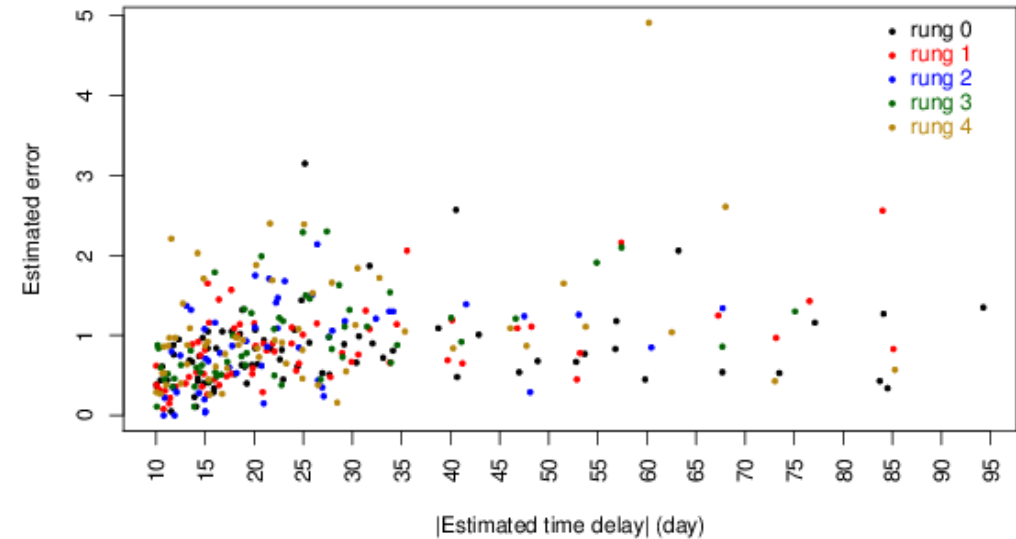
For Rung 3,

$$\text{if } |\tilde{\Delta}t| \leq 30 \Rightarrow \sigma_R = 0.08 \times |\tilde{\Delta}t|, \quad \text{if } |\tilde{\Delta}t| > 30 \Rightarrow \sigma_R = 1.5$$

For Rung 4,

$$\text{if } |\tilde{\Delta}t| \leq 25 \Rightarrow \sigma_R = 0.08 \times |\tilde{\Delta}t|, \quad \text{if } |\tilde{\Delta}t| > 25 \Rightarrow \sigma_R = 1.5$$

$$\sigma_{\tilde{\Delta}t_{A_1 A_2}} = \sqrt{(\sigma_{\tilde{\Delta}t_{A_1 A_2}}^{ini})^2 + \sigma_R^2}$$



Results: TDC1 paper

STRONG LENS TIME DELAY CHALLENGE: II. RESULTS OF TDC1

KAI LIAO^{1,2*}, TOMMASO TREU^{2*}, PHIL MARSHALL³, CHRISTOPHER D. FASSNACHT⁴, NICK RUMBAUGH⁴, GREGORY DOBLER^{5,20}, AMIR AGHAMOUSA⁹, VIVIEN BONVIN¹³, FREDERIC COURBIN¹³, ALIREZA HOJJATI^{6,7}, NEAL JACKSON¹², VINAY KASHYAP¹⁷, S. RATHNA KUMAR¹⁴, ERIC LINDER^{8,18}, KAISEY MANDEL¹⁷, XIAO-LI MENG¹⁵, GEORGES MEYLAN¹³, LEONIDAS A. MOUSTAKAS¹¹, TUSHAR P. PRABHU¹⁴, ANDREW ROMERO-WOLF¹¹, ARMAN SHAFIELOO^{9,10}, ANETA SIEMIGINOWSKA¹⁷, CHELLIAH S. STALIN¹⁴, HYUNGSUK TAK¹⁵, MALTE TEWES¹⁹, AND DAVID VAN DYK¹⁶

Draft version September 5, 2014

ABSTRACT

We present the results of the first strong lens time delay challenge. The motivation, experimental design, and entry level challenge are described in a companion paper. This paper presents the main challenge, TDC1, which consisted in analyzing thousands of simulated light curves blindly. The observational properties of the light curves cover the range in quality obtained for current targeted efforts (e.g. COSMOGRAIL) and expected from future synoptic surveys (e.g. LSST), and include “evilness” in the form of simulated systematic errors. 7 teams participated in TDC1, submitting results from 78 different method variants. After a describing each method, we compute and analyze basic statistics measuring accuracy (or bias) A , goodness of fit χ^2 , precision P , and success rate f . For some methods we identify outliers as an important issue. Other methods show that outliers can be controlled via visual inspection or conservative quality control. Several methods are competitive, i.e. give $|A| < 0.03$, $P < 0.03$, and $\chi^2 < 1.5$, with some of the methods already reaching sub-percent accuracy. The fraction of light curves yielding a time delay measurement is typically in the range $f = 20\text{--}40\%$. It depends strongly on the quality of the data: COSMOGRAIL-quality cadence and light curve lengths yield significantly higher f than does sparser sampling. We estimate that LSST should provide around 400 robust time-delay measurements, each with $P < 0.03$ and $|A| < 0.01$, comparable to current lens modeling uncertainties. In terms of observing strategies, we find that A and f depend mostly on season length, while P depends mostly on cadence and campaign duration.

Subject headings: gravitational lensing — methods: data analysis

$$f \equiv \frac{N_{\text{submitted}}}{N}$$

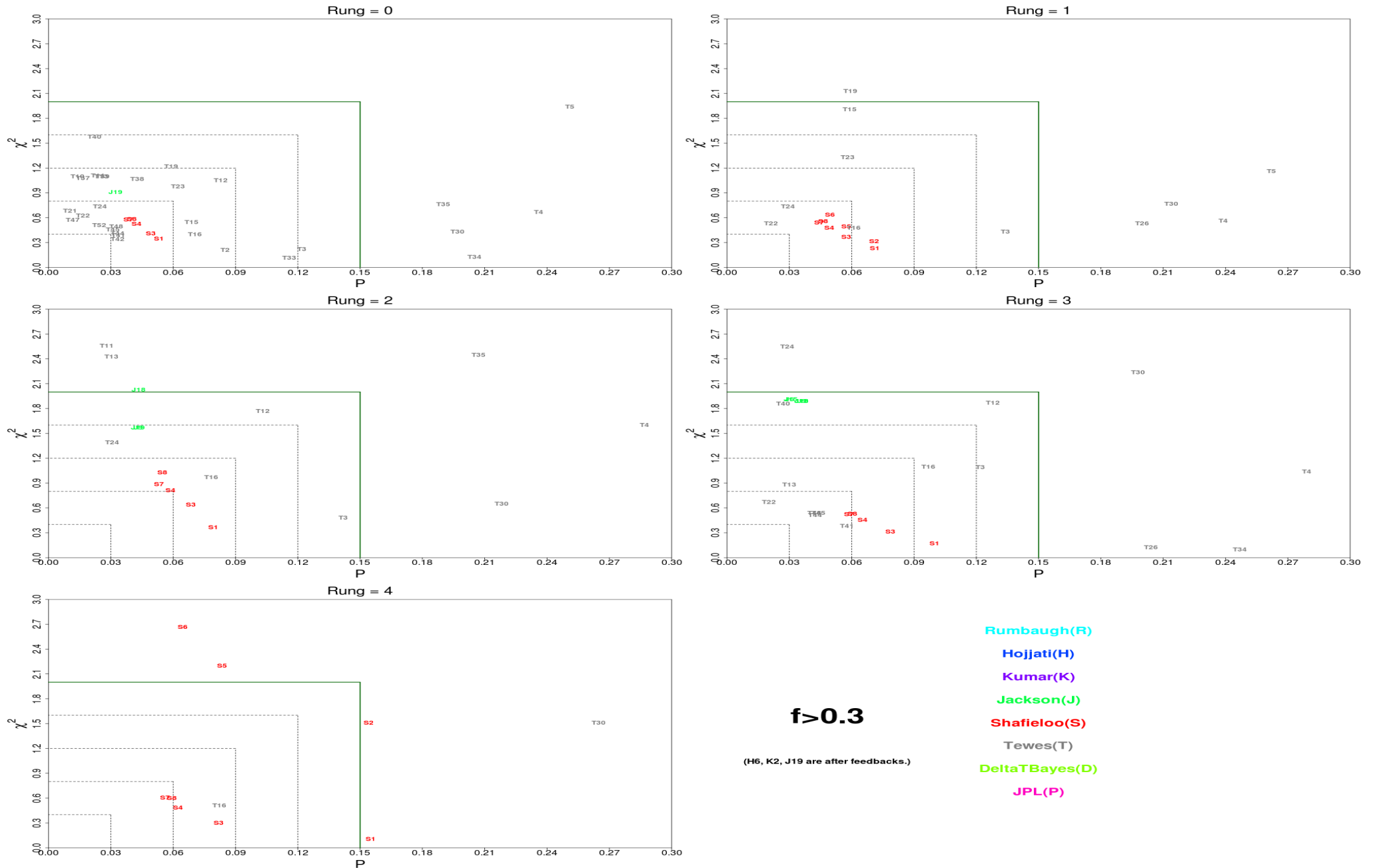
$$P = \frac{1}{fN} \sum_i \left(\frac{\sigma_i}{|\Delta t_i|} \right)$$

$$A = \frac{1}{fN} \sum_i \left(\frac{|\tilde{\Delta t}_i| - |\Delta t_i|}{|\Delta t_i|} \right)$$

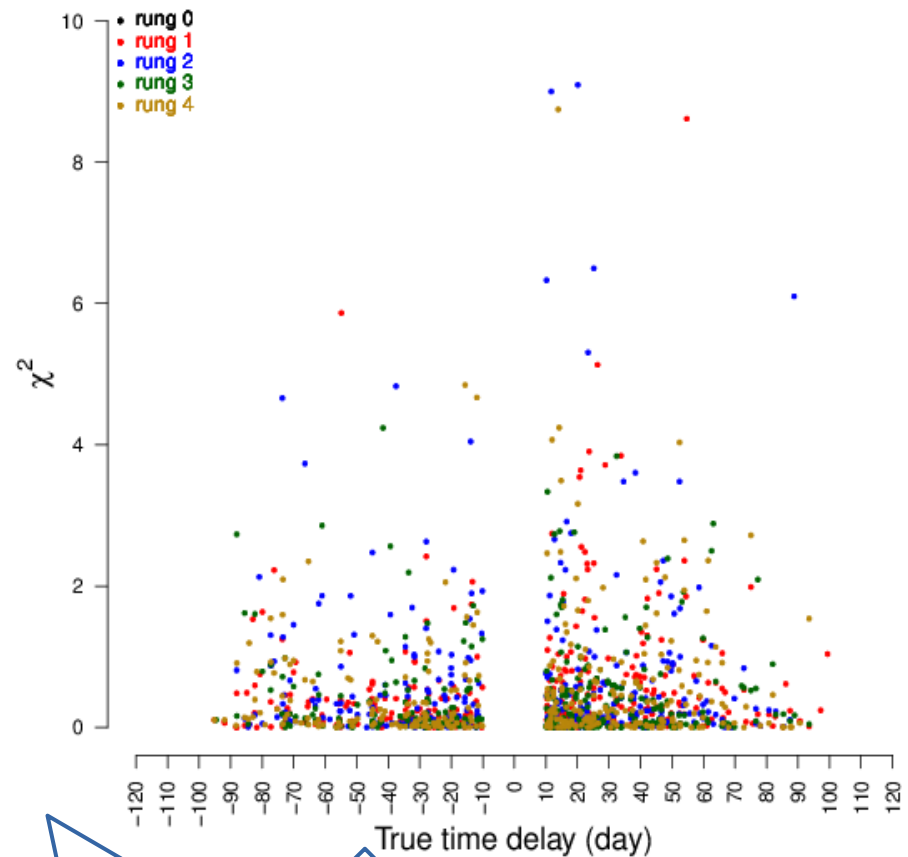
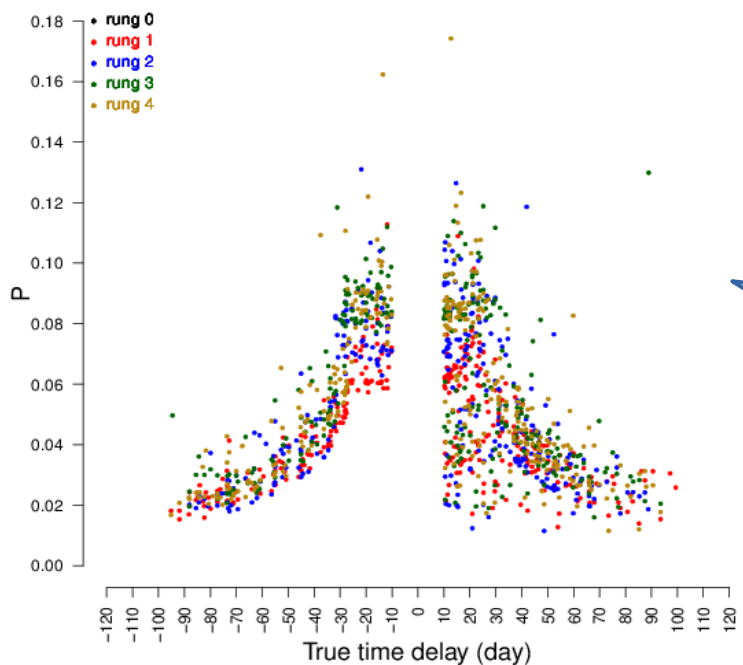
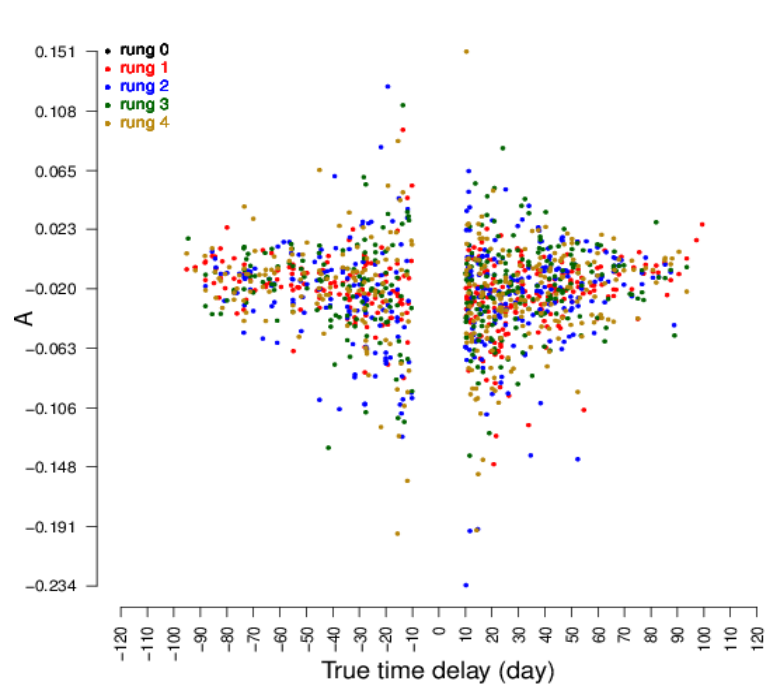
$$\chi^2 = \frac{1}{fN} \sum_i \left(\frac{\tilde{\Delta t}_i - \Delta t_i}{\sigma_i} \right)^2$$

Rung	f	χ^2	P	A
0	0.529	0.579	0.038	-0.018
1	0.366	0.543	0.044	-0.022
2	0.350	0.885	0.053	-0.025
3	0.337	0.524	0.059	-0.021
4	0.346	0.608	0.056	-0.024

Results: estimated vs true time delay



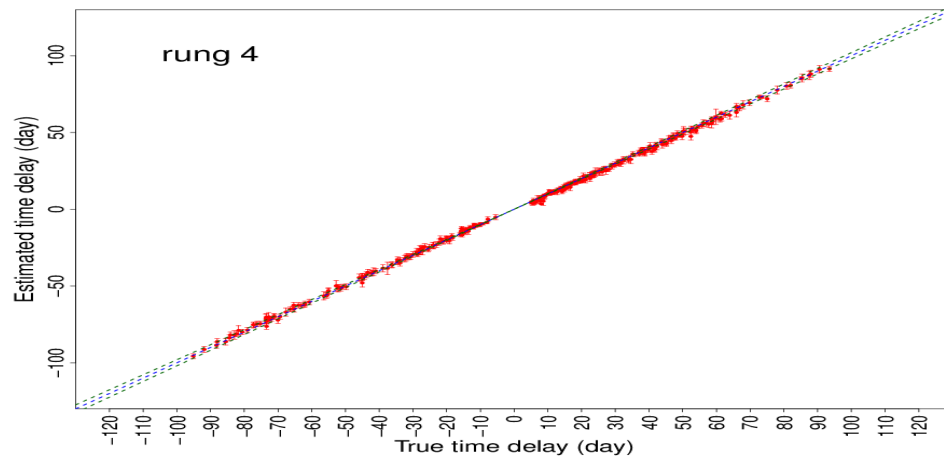
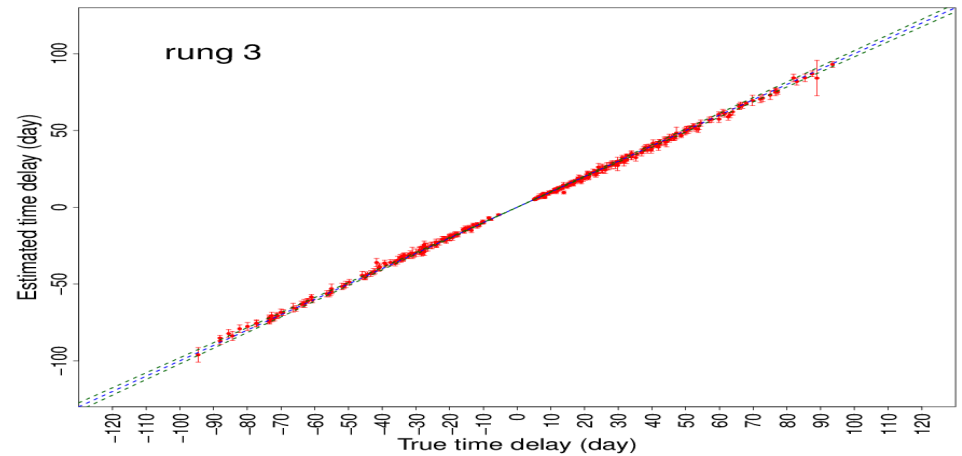
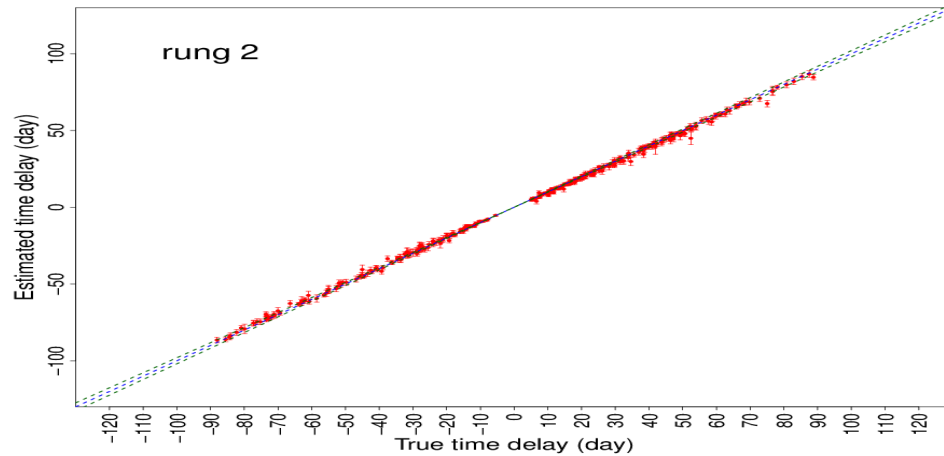
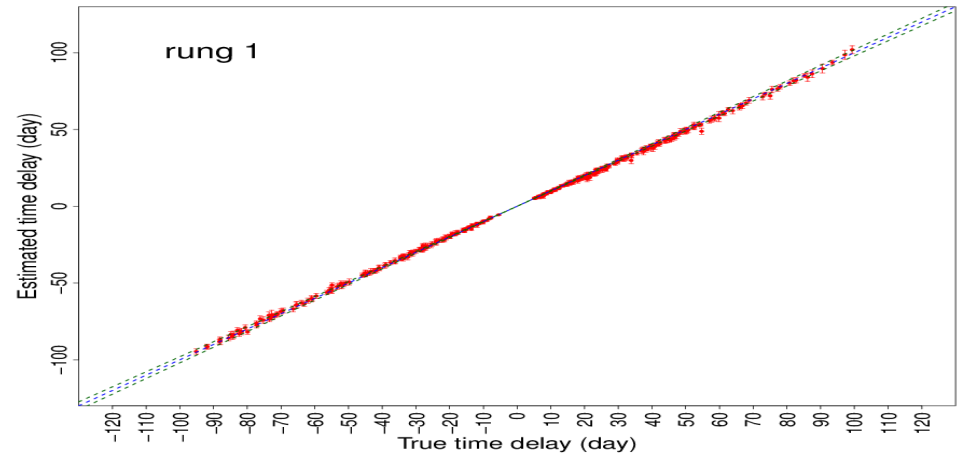
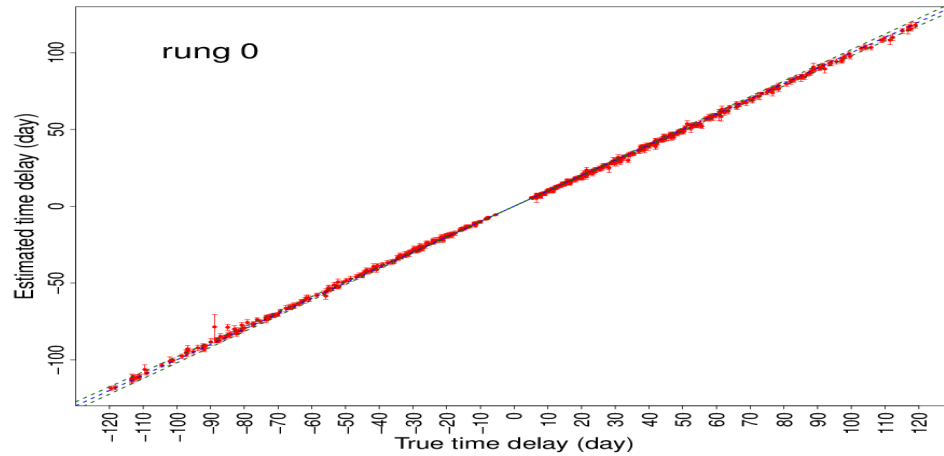
Results: histogram of metrics



there are only 5 items with
 $\chi^2 \geq 10$
out of few thousand entries

(Aghamoussa, Shafieloo, APJ, 2015)

Results: estimated vs true time delay



Results: calibration

Rung	f	χ^2	P	A
0	0.529	0.579	0.038	-0.018
1	0.366	0.543	0.044	-0.022
2	0.350	0.885	0.053	-0.025
3	0.337	0.524	0.059	-0.021
4	0.346	0.608	0.056	-0.024



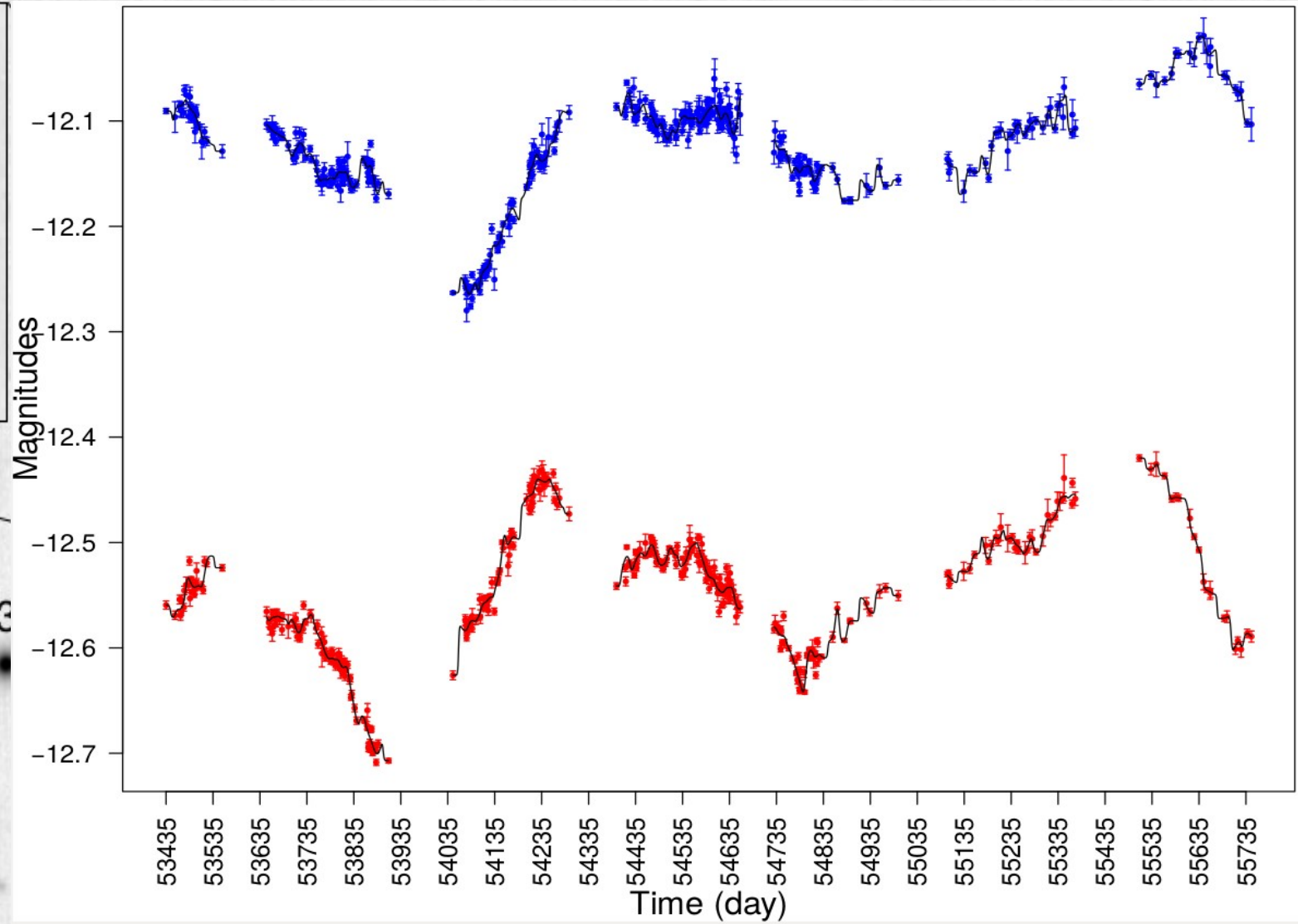
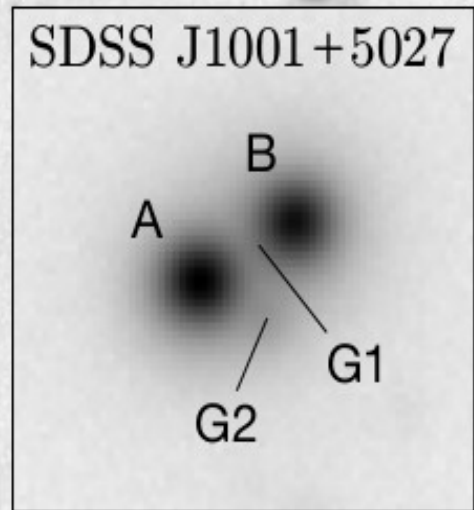
$$\tilde{\Delta}t_i + 0.5 \quad \text{and} \quad \sigma_i/\sqrt{2}$$



Rung	f	χ^2	P	A
0	0.529	0.792	0.027	-0.0014
1	0.366	0.660	0.031	-0.0036
2	0.350	1.439	0.038	-0.0058
3	0.337	0.766	0.041	-0.0010
4	0.346	0.868	0.040	-0.0048

Time delay estimation of SDSS J1001+5027

Light curves



1'

E

Methodology

algorithm

$$A^s(t) = A^g(t) + N(t) \sum_i \frac{A^d(t_i) - A^g(t_i)}{\sigma_d^2(t_i)} \times \exp \left[-\frac{(t_i - t)^2}{2\Delta^2} \right]$$

Weighted Correlation:

$$r_w = \frac{\sum_{i=1}^n w_i (x_i - \bar{x}_w)(y_i - \bar{y}_w)}{\sqrt{\sum_{i=1}^n w_i (x_i - \bar{x}_w)^2 \sum_{i=1}^n w_i (y_i - \bar{y}_w)^2}}$$

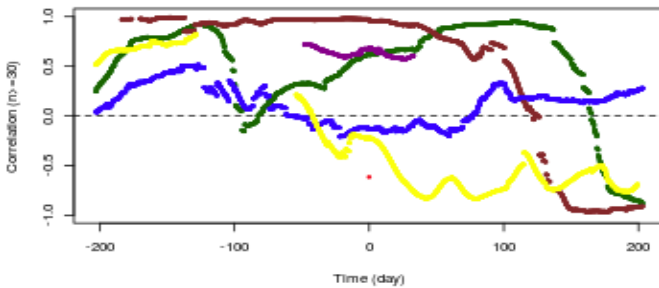
$$\bar{x}_w = \sum_{i=1}^n w_i x_i, \quad \bar{y}_w = \sum_{i=1}^n w_i y_i \quad w_i = \frac{1}{\sigma_i^2}$$

$\Delta = ?$

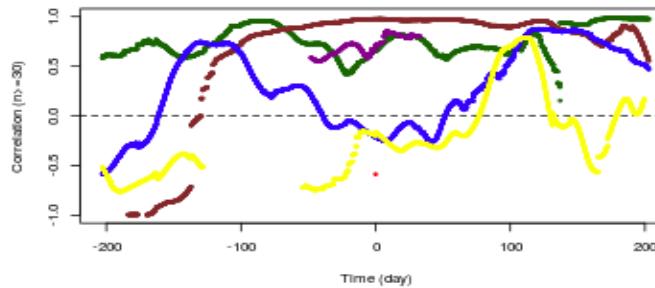
$n = ?$

Mean or Mirror estimator?

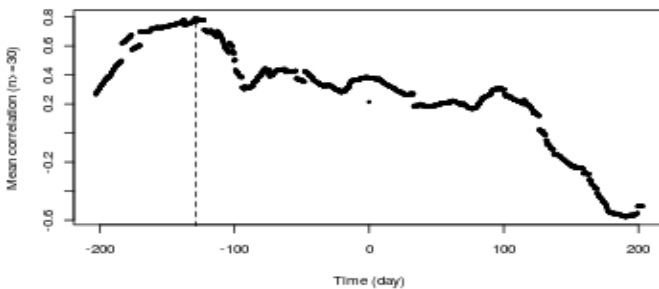
cor.sa.db.matrix



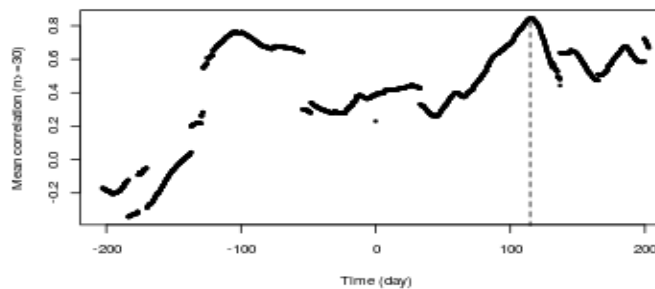
cor.sb.da.matrix



cor.sa.db.matrix, Best lag = -128.6



cor.sb.da.matrix, Best lag = 114.8

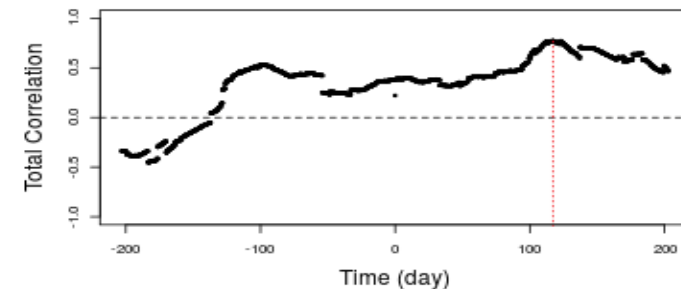


Weighted Correlation

Delta = 8, n>30

Mean = 121.7 Mirror = 117.1

Cor=0.77, Best lag = 117.1



Simulation

$$n > 3$$

$$n > 30$$

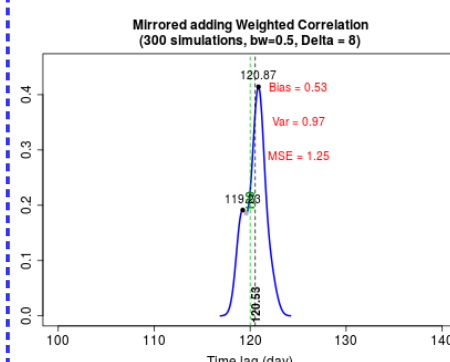
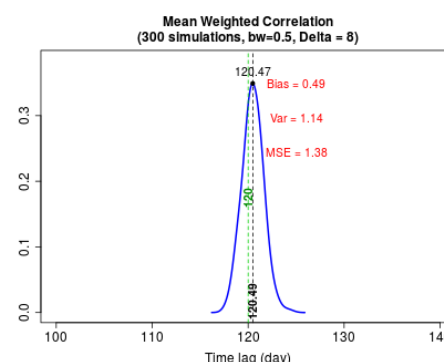
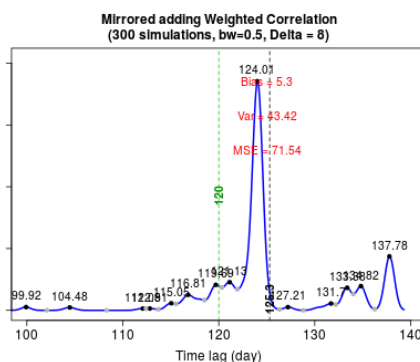
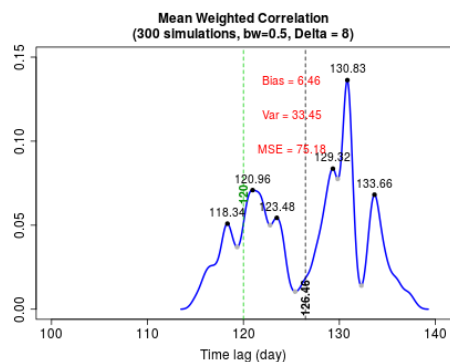
Mean

Mirror

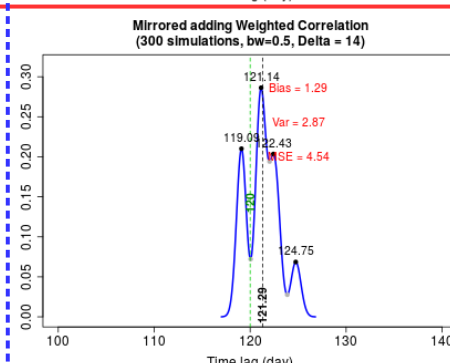
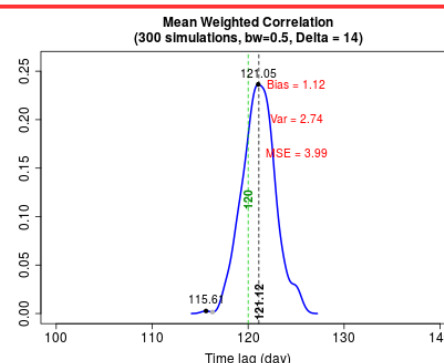
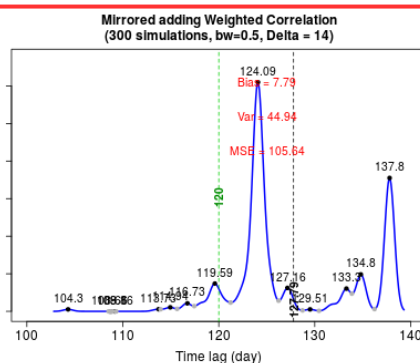
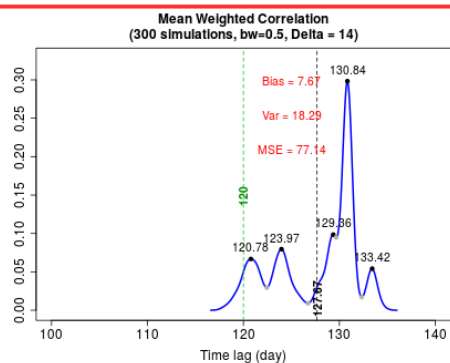
Mean

Mirror

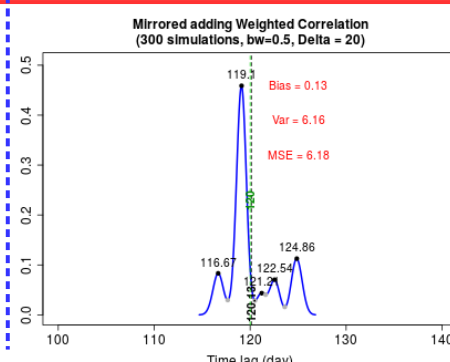
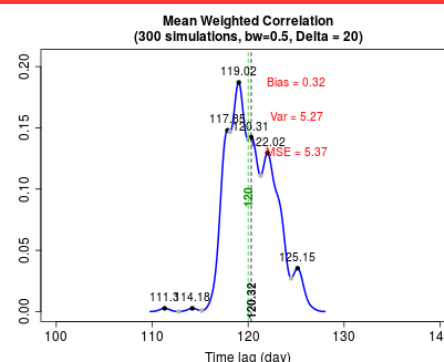
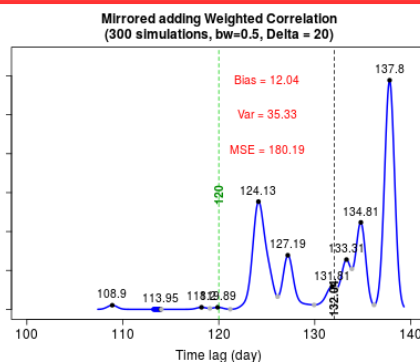
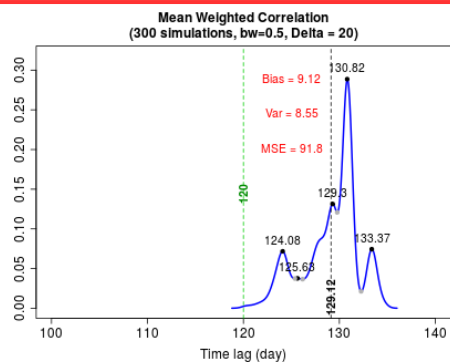
$$\Delta = 8$$



$$\Delta = 14$$



$$\Delta = 20$$



Mean Squared Error (MSE)

$\hat{\theta}_n$ is the **estimator** of θ **unknown parameter/value**.

Bias:

$$\text{Bias}(\hat{\theta}_n) = \mathbb{E}(\hat{\theta}_n) - \theta$$

Variance:

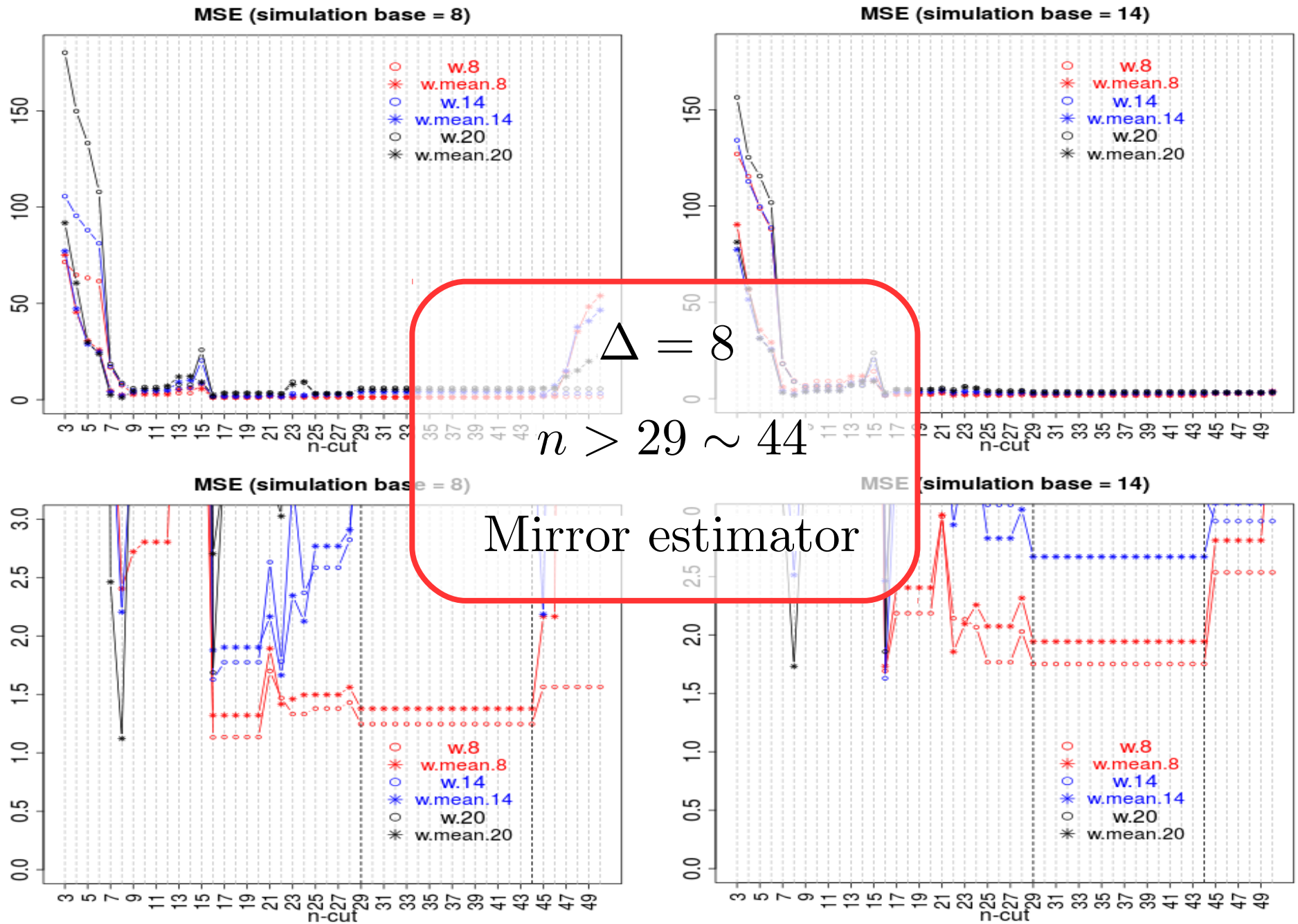
$$\text{Var}(\hat{\theta}_n) = \mathbb{E} \left[(\hat{\theta}_n - \bar{\theta}_n)^2 \right] \quad \text{where} \quad \bar{\theta}_n = \mathbb{E}(\hat{\theta}_n)$$

Mean Squared Error (MSE)

$$\text{MSE}(\hat{\theta}_n) = \mathbb{E} \left[(\hat{\theta}_n - \theta)^2 \right] = \dots = \left(\mathbb{E}(\hat{\theta}_n) - \theta \right)^2 + \mathbb{E} \left[(\hat{\theta}_n - \bar{\theta}_n)^2 \right]$$

$$\text{MSE} = \text{Bias}^2 + \text{Var}$$

Optimum estimator



Error estimation

- Confidence set.**

$$\mathbb{P}(a \leq \theta \leq b) = (1 - \alpha) \equiv \psi\%$$

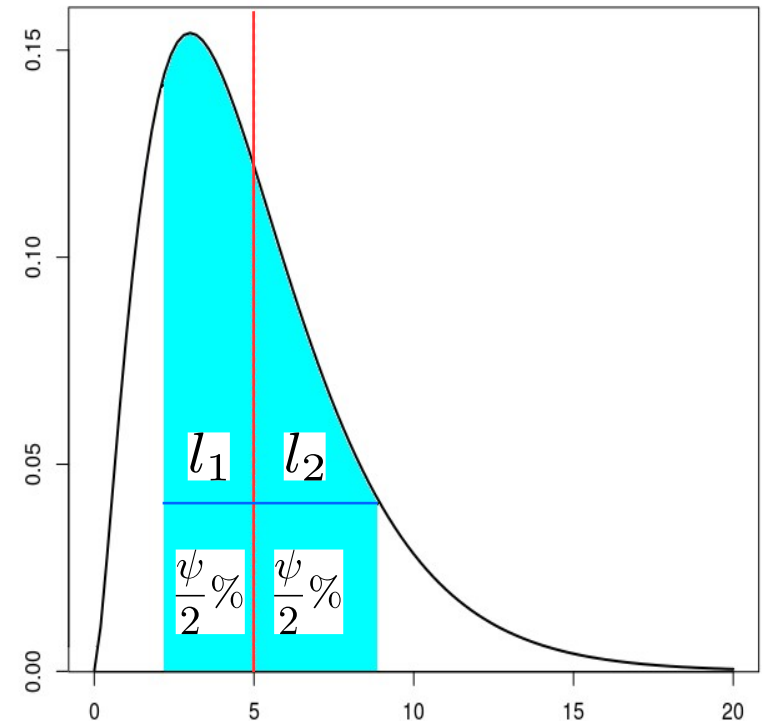
- To find a confidence interval we need the **probability distribution of estimator** which can be known from **statistical properties of estimator** or can be achieved by **simulation**.
- In some cases we know the probability distribution of a quantity which has a relation to estimator.

$$\mathbb{P}\left(\mathbb{E}(\hat{\theta}_n) - l_1 \leq \hat{\theta}_n \leq \mathbb{E}(\hat{\theta}_n) + l_2\right) = (1 - \alpha) \equiv \psi\%$$

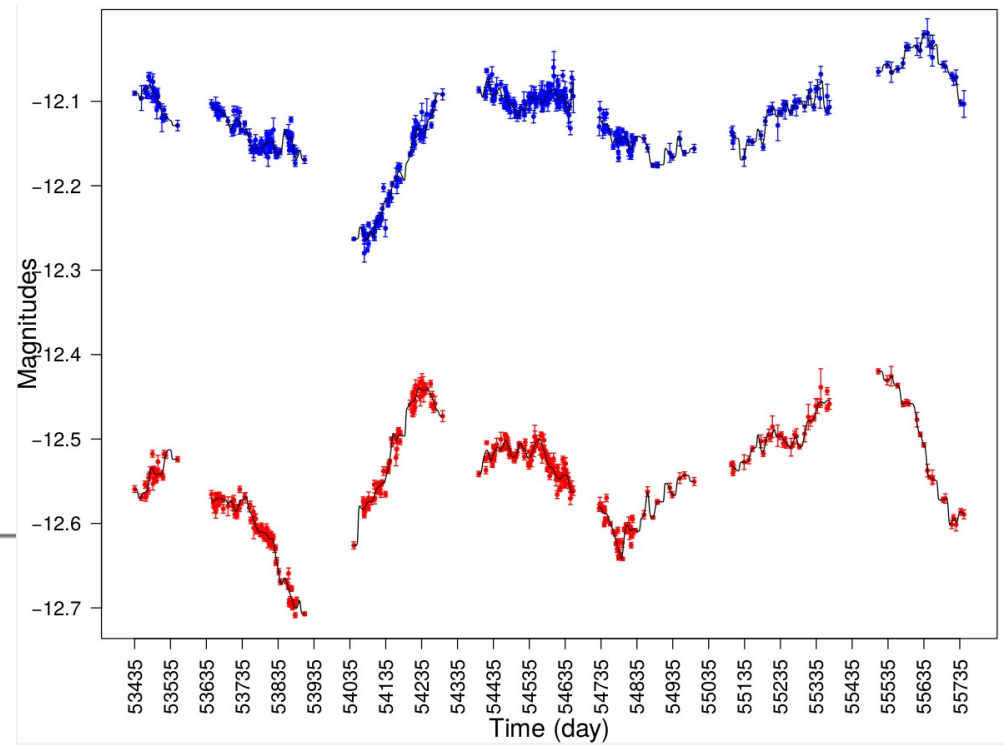
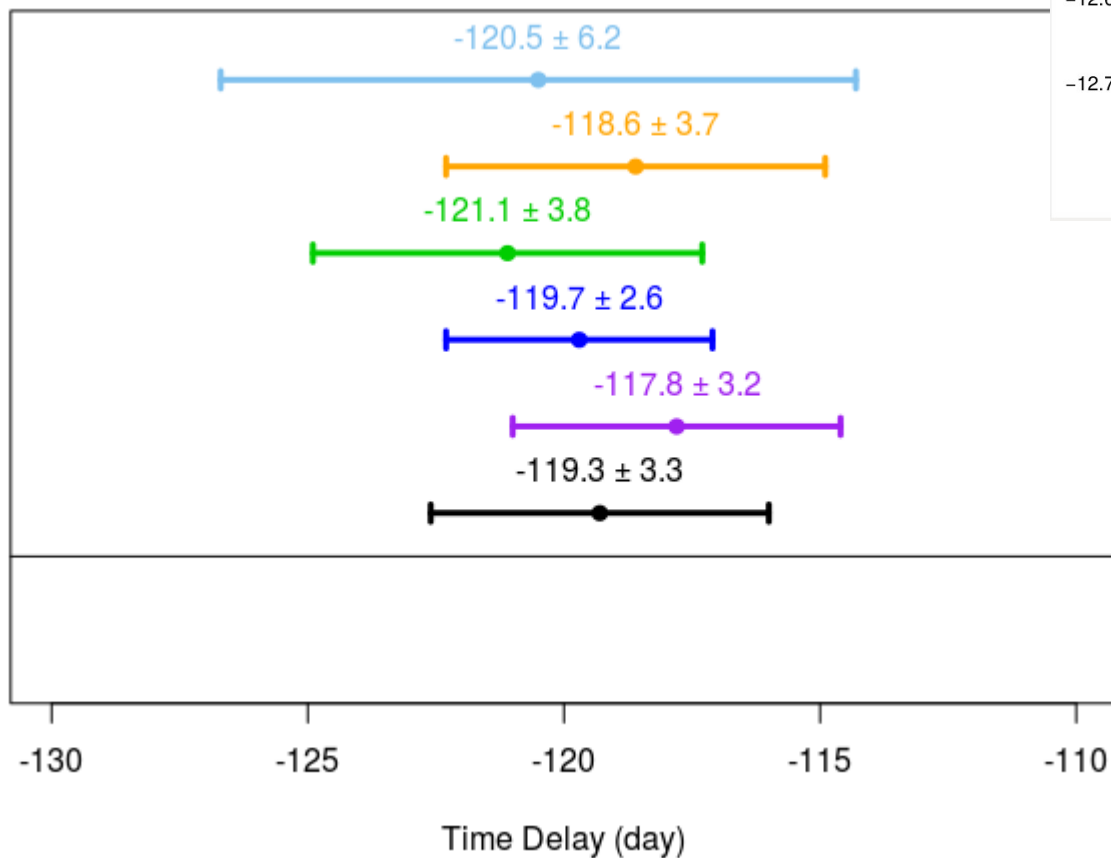
$$\mathbb{P}\left(\mathbb{E}(\hat{\theta}_n) - \theta - l_1 \leq \hat{\theta}_n - \theta \leq (\mathbb{E}(\hat{\theta}_n) - \theta) + l_2\right)$$

$$\mathbb{P}\left(\underbrace{\hat{\theta} - l_2 - \overbrace{(\mathbb{E}(\hat{\theta}) - \theta)}^{\text{Bias}}}_a \leq \theta \leq \underbrace{\hat{\theta} + l_1 - \overbrace{(\mathbb{E}(\hat{\theta}) - \theta)}^{\text{Bias}}}_b\right)$$

$$\mathbb{P}(a \leq \theta \leq b) = (1 - \alpha) \equiv \psi\%$$



Results



$$\Delta = 8$$

$$n > 29 \sim 44$$

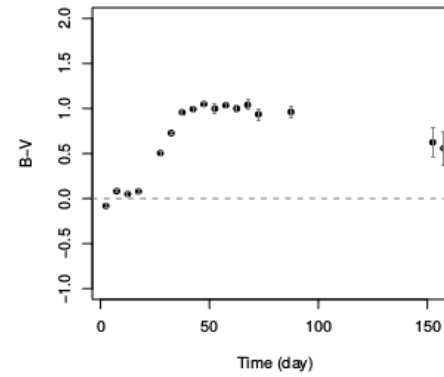
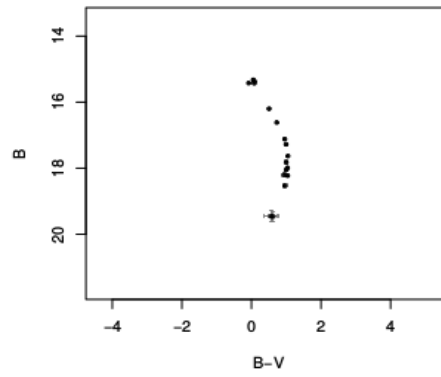
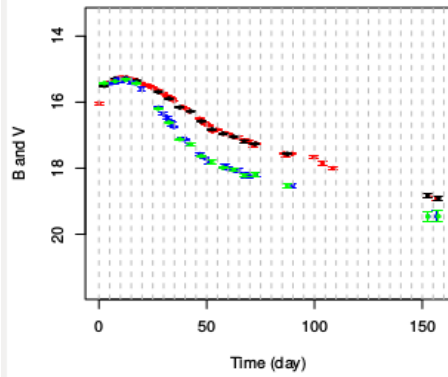
Mirror estimator

$$\mathbb{P}(a \leq \theta \leq b) = (1 - \alpha) \equiv \psi\%$$

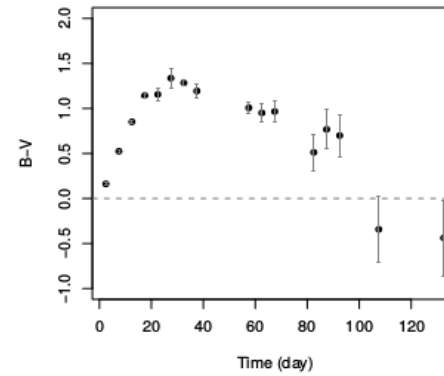
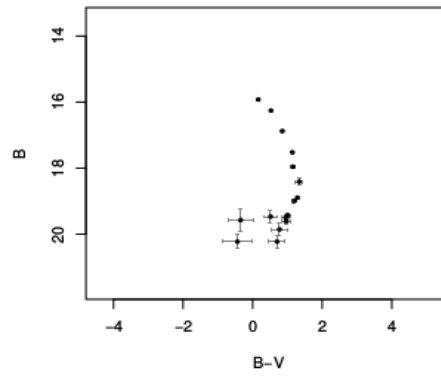
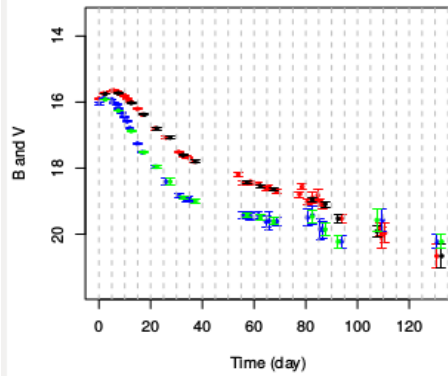
Supernova Type Ia classification

Binned light curves

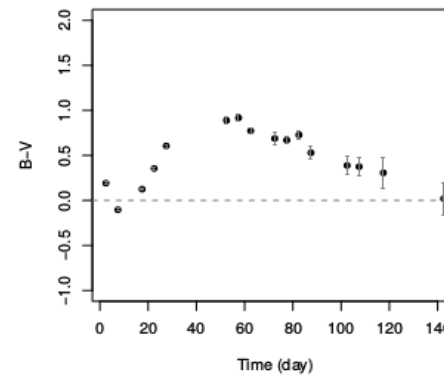
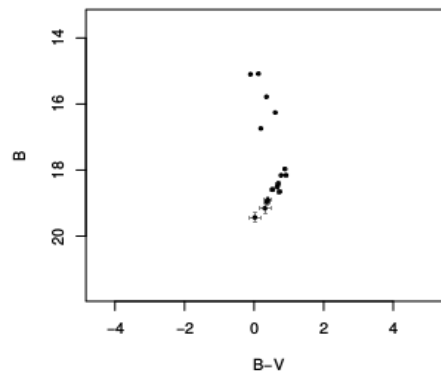
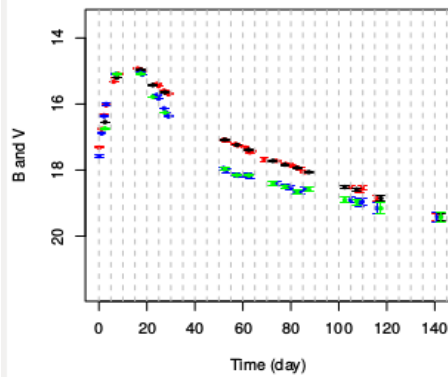
2009dc, bin=5 days



2007hj, bin=5 days

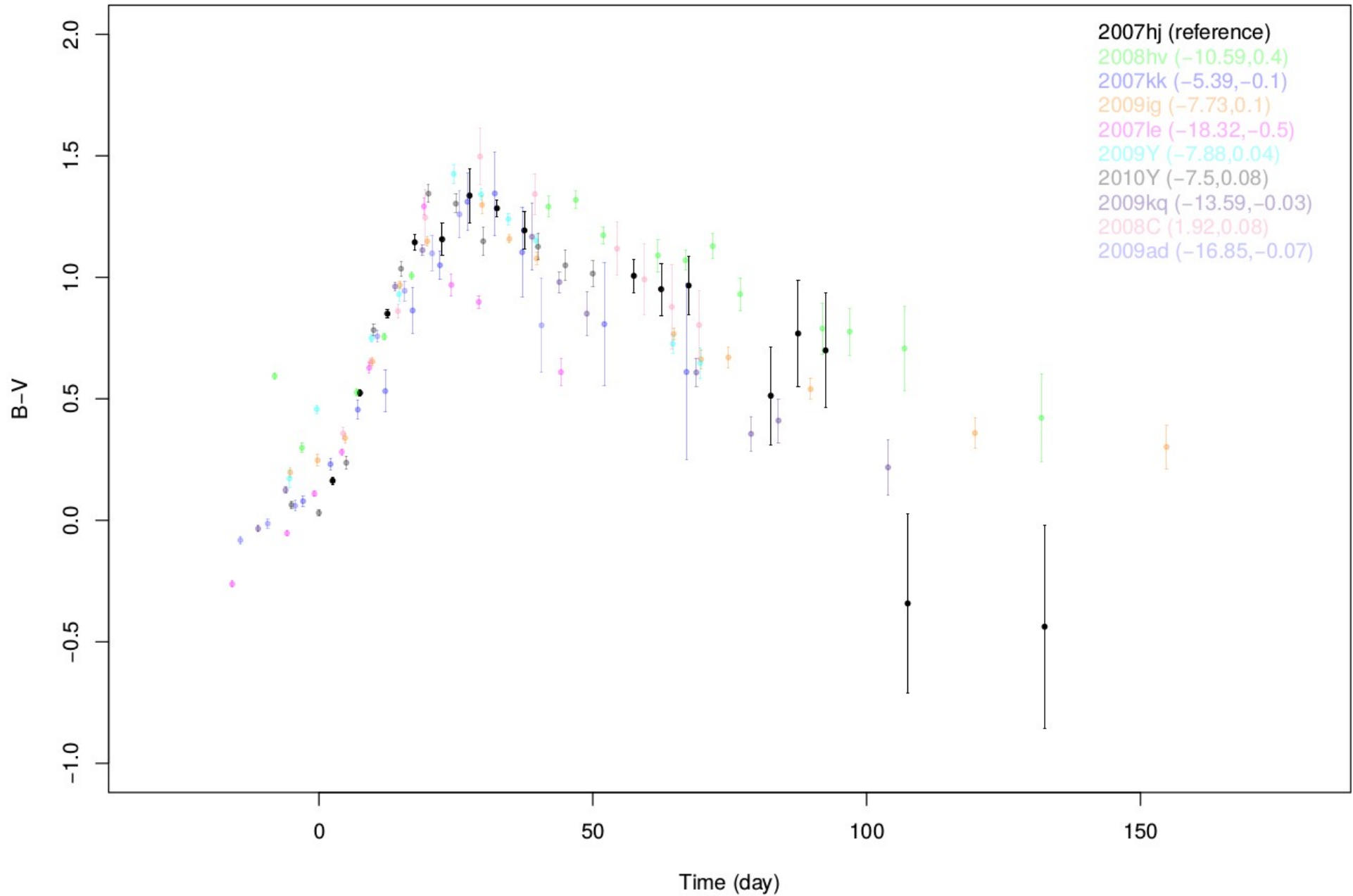


2008hv, bin=5 days



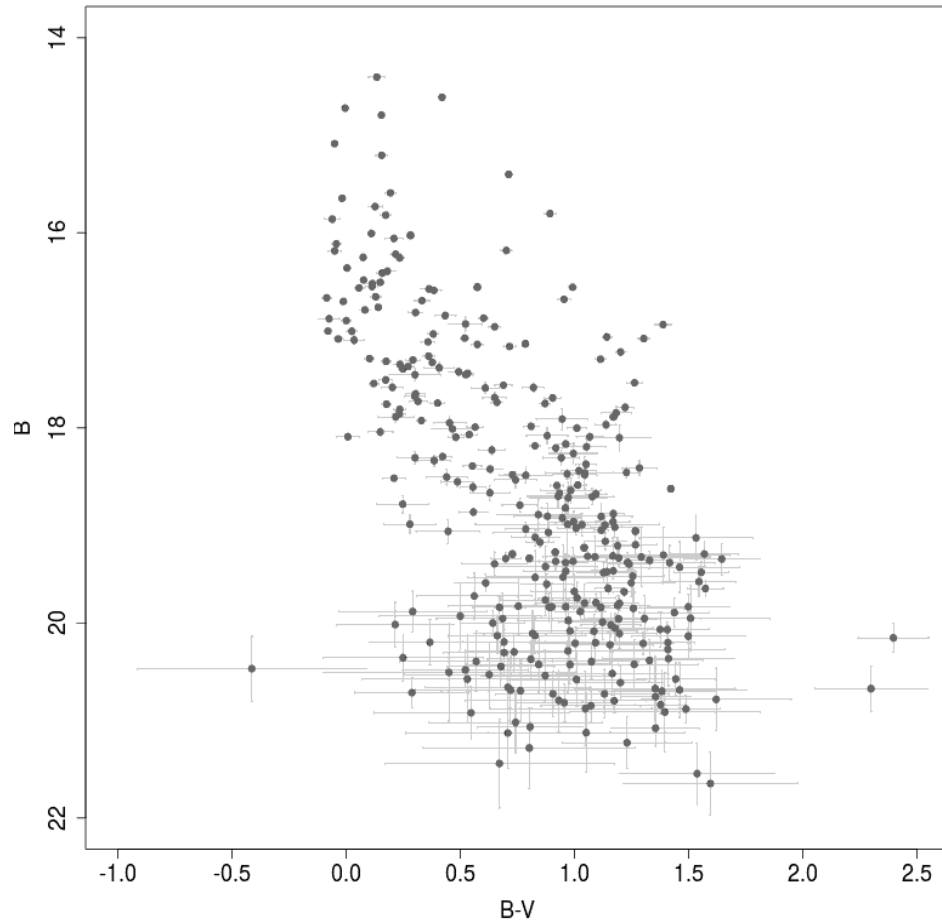
Results

10 SNe, pair comparison, best Likelihood of 100 optimizations

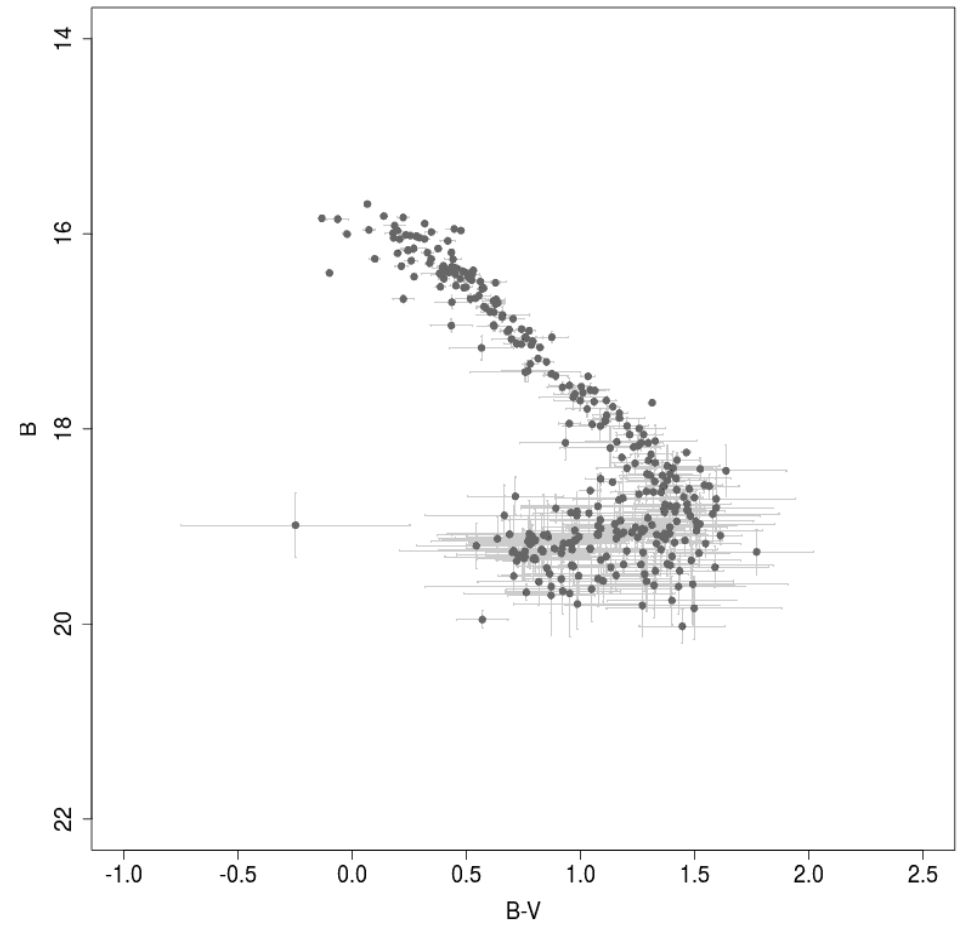


Results

45 Type Ia supernovae (before shifting)

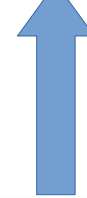
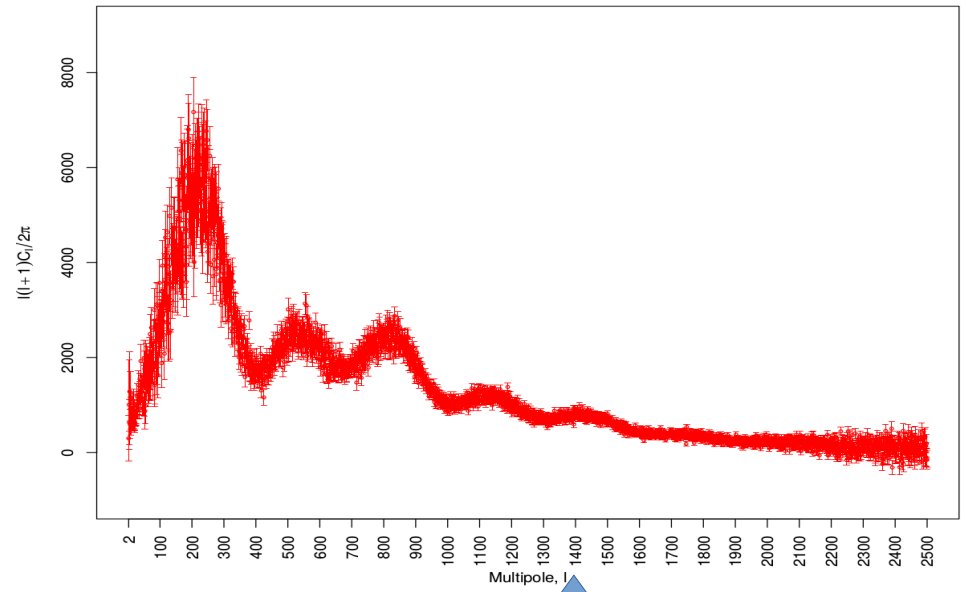
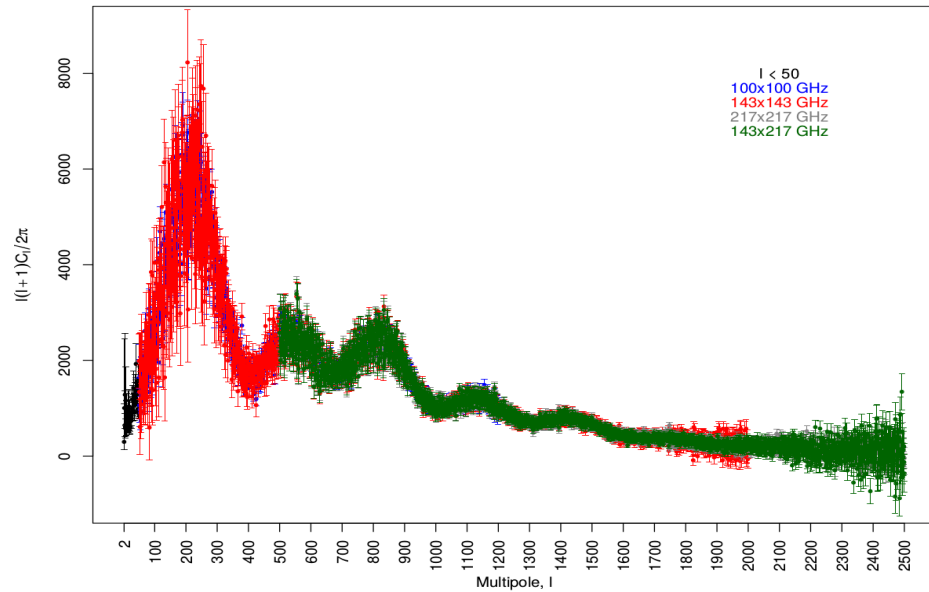


45 Type Ia supernovae (after shifting)



Model-independent estimation of CMB angular power spectrum

CMB Angular power spectrum data



$$\bar{\mathcal{D}}_\ell = \frac{\sum_{ch} w_\ell^{ch} \mathcal{D}_\ell^{ch}}{\sum_{ch} w_\ell^{ch}}, \quad w_\ell^{ch} = (\sigma_\ell^{ch})^{-2}$$

$$\text{Cov}(\bar{\mathcal{D}}_\ell, \bar{\mathcal{D}}_{\ell'}) = \frac{1}{\sum_{ch} w_\ell^{ch} \sum_{ch'} w_{\ell'}^{ch'}} \sum_{ch, ch'} w_\ell^{ch} w_{\ell'}^{ch'} \text{Cov}(\mathcal{D}_\ell^{ch}, \mathcal{D}_{\ell'}^{ch'})$$

Parametric regression

$$Y_i = f(x_i) + \epsilon_i$$

- Assume $f(x) = ax + b$.
- Assume noise $\epsilon_i \sim N(0, \sigma^2)$ IID.
- Likelihood function

$$L(a, b|\text{data}) = \prod_{i=1}^n \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(\frac{-(Y_i - (ax_i + b))^2}{2\sigma^2}\right)$$

- To estimate a, b : Maximize $L(a, b|\text{data})$ w.r.t. a, b .
- This is same as linear least-squares regression, under the assumptions made.

REACT: nonparametric regression

- $Y_i = f(x_i) + \epsilon_i$, with $\epsilon_i \sim N(0, \sigma^2)$ IID, σ^2 known.
- Assume $f \in L_2(a, b)$ and a complete orthonormal basis $\{\phi_j(x)\}$.

$$f(x) = \sum_{j=0}^{\infty} \beta_j \phi_j(x), \quad \beta_j = \int_a^b f(x) \phi_j(x) dx$$

- Regression estimator $\hat{f}(x)$:

$$f(x) = \sum_{j=0}^{n-1} \hat{\beta}_j \phi_j(x) + (\text{some truncation bias})$$

$$\hat{\beta}_j := \lambda_j Z_j \text{ with } 1 \geq \lambda_0 \geq \dots \geq \lambda_{n-1} \geq 0. \quad \text{and} \quad Z_j = \sum_{i=1}^n Y_i \phi_j(x_i)$$

- Inverse-noise-weighted squared loss function

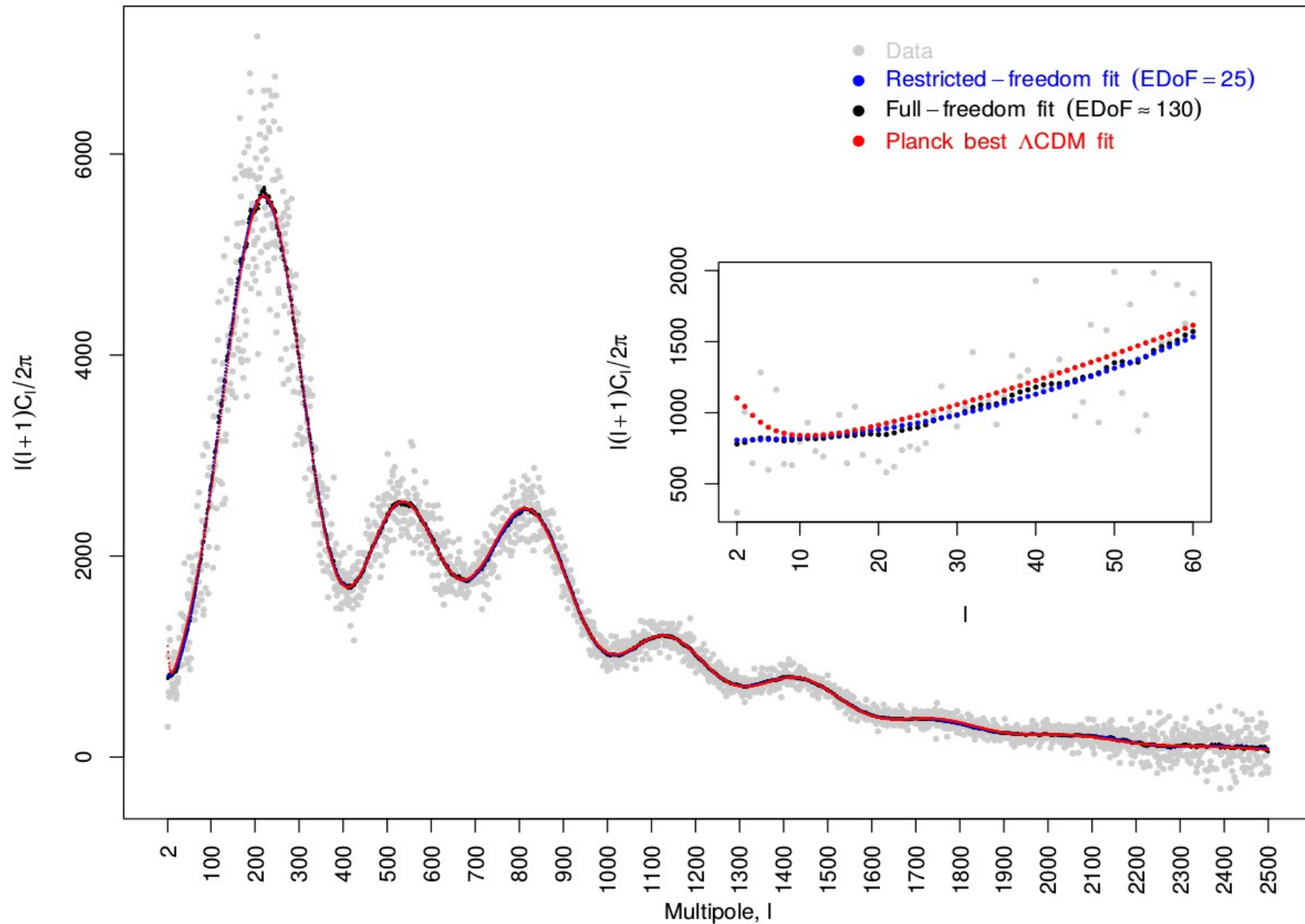
$$L(\hat{f}, f) = \int \left(\frac{\hat{f}(x) - f(x)}{\sigma(x)} \right)^2 dx.$$

- Risk estimator

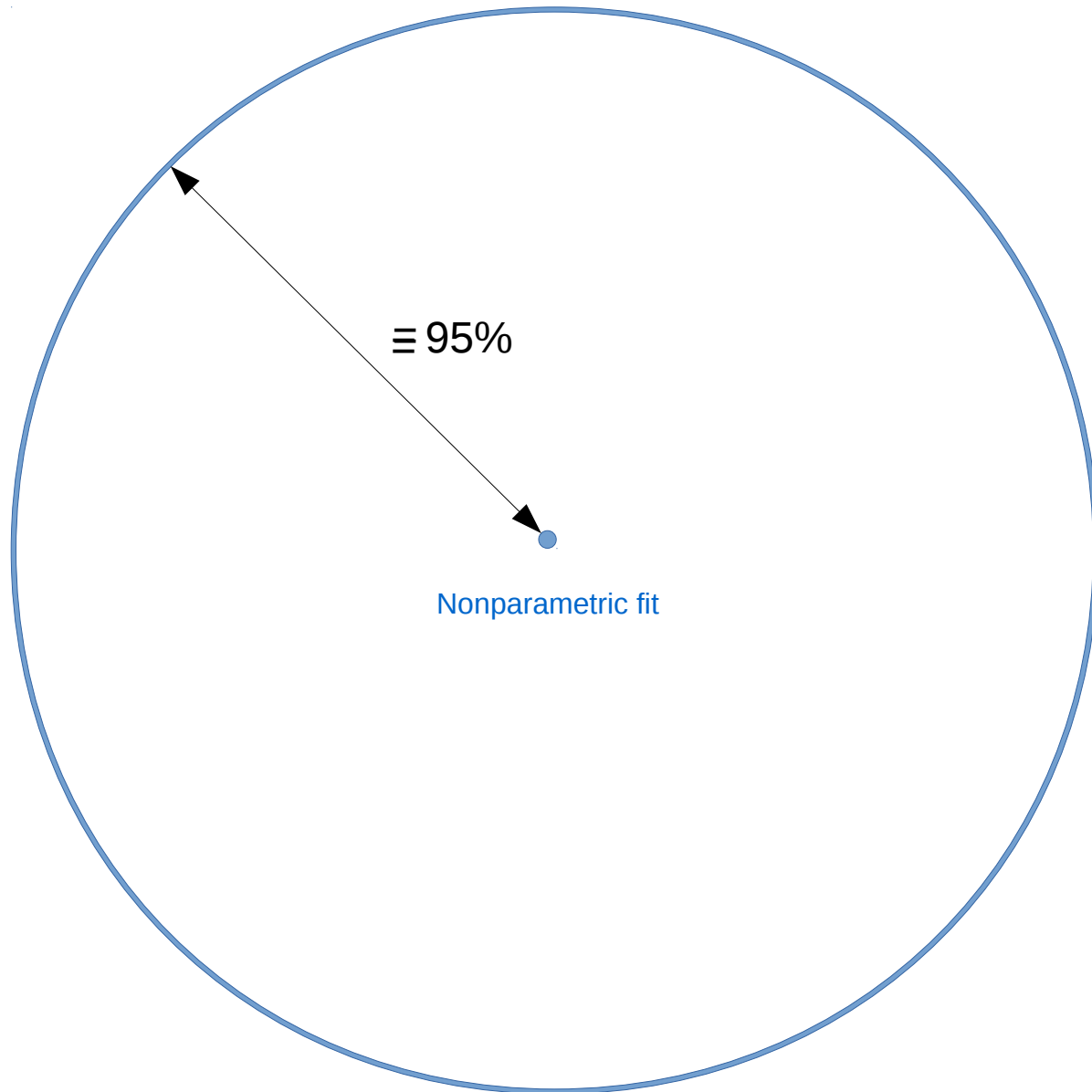
$$\hat{R}(\lambda) = Z^T \bar{D} W \bar{D} Z + \text{tr}(DWDB) - \text{tr}(\bar{D} W \bar{D} B),$$

subject to the constraint $1 \geq \lambda_0 \geq \dots \geq \lambda_{n-1} \geq 0$.

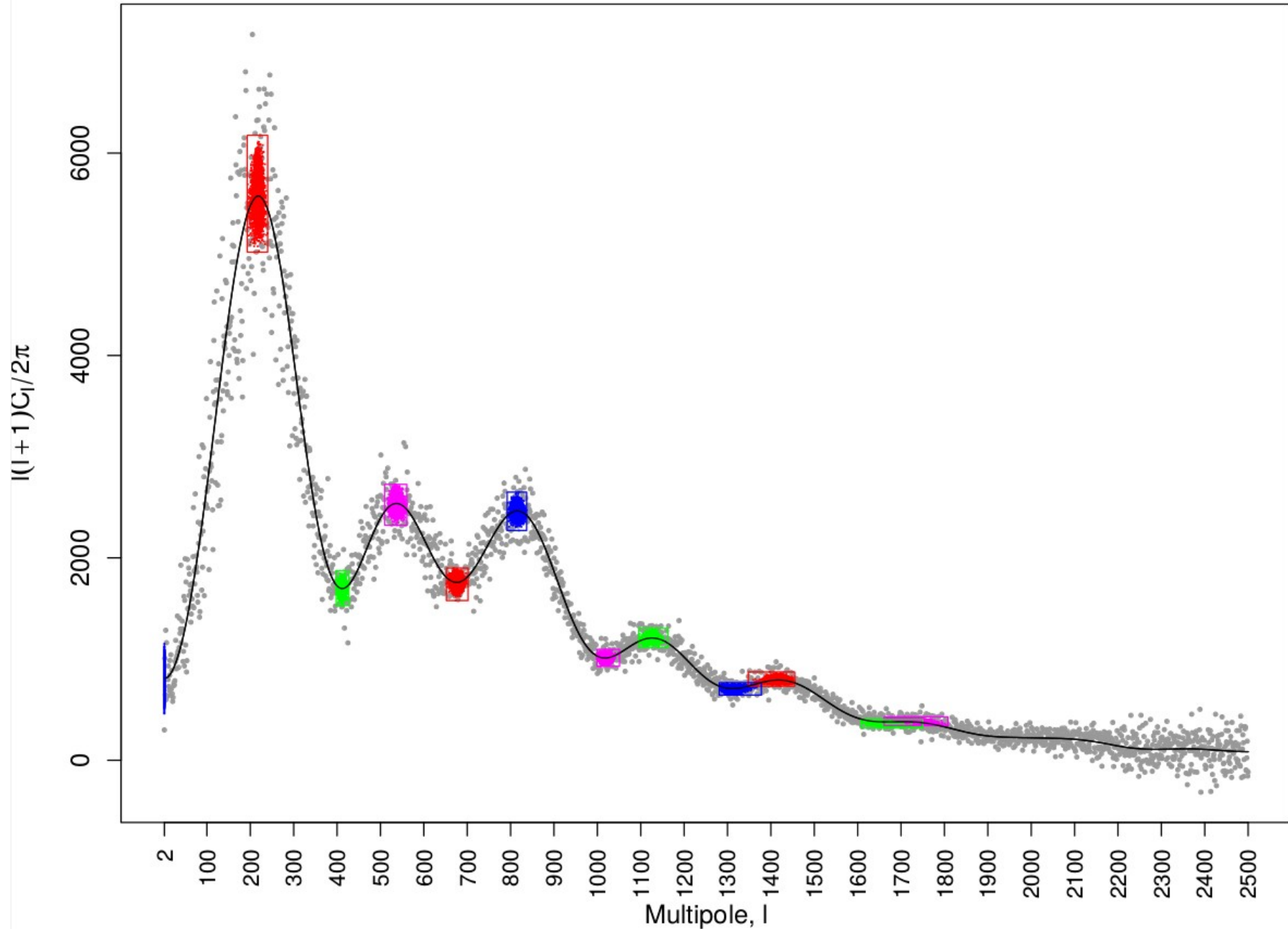
Planck 2013 power spectrum estimation



Confidence set in Function space

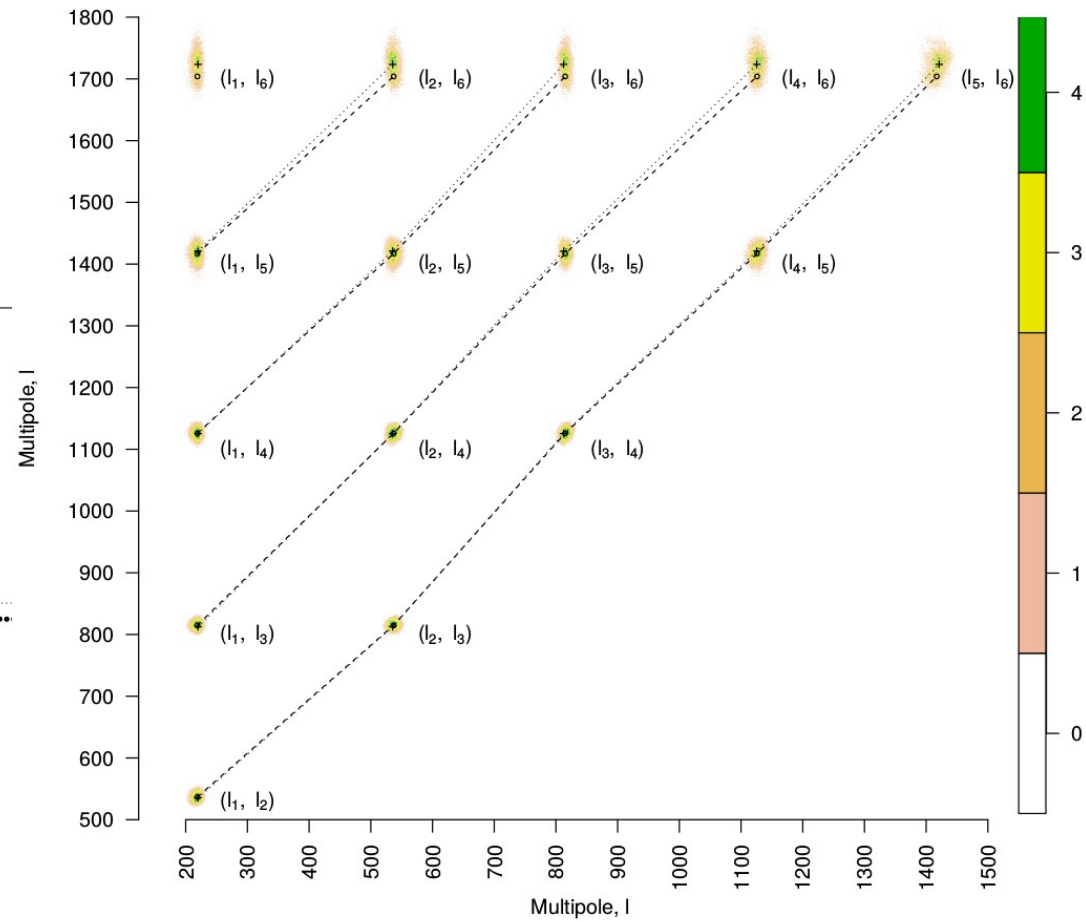
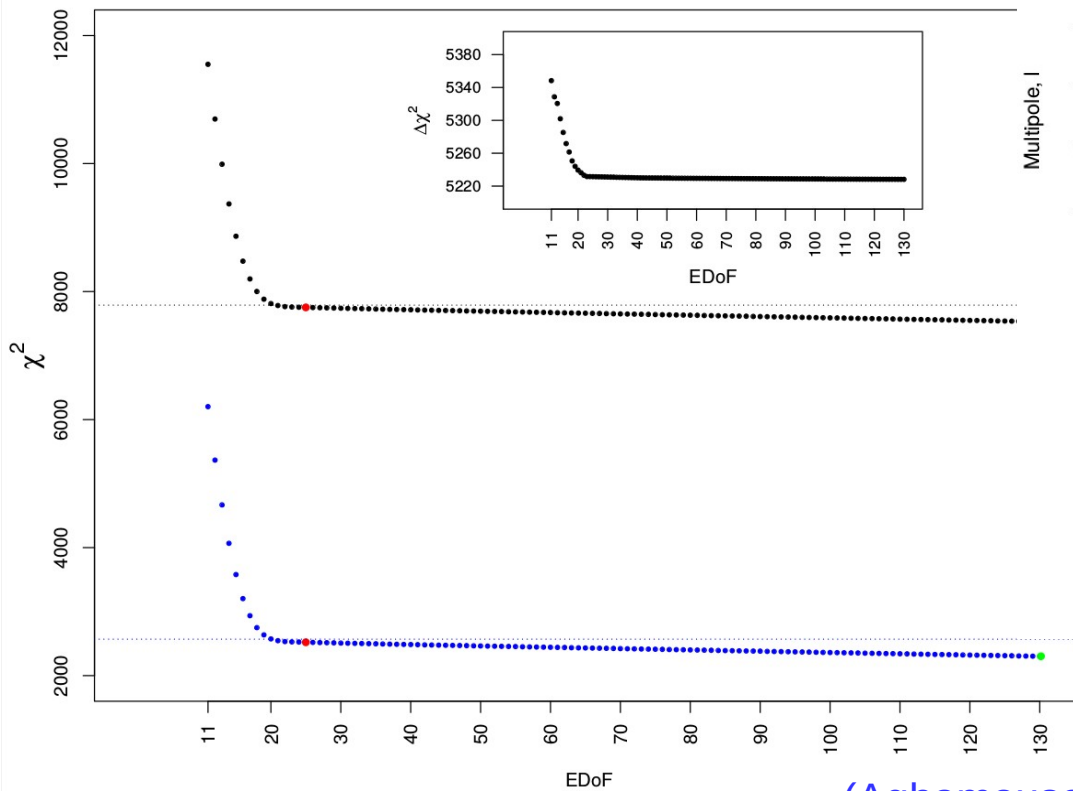
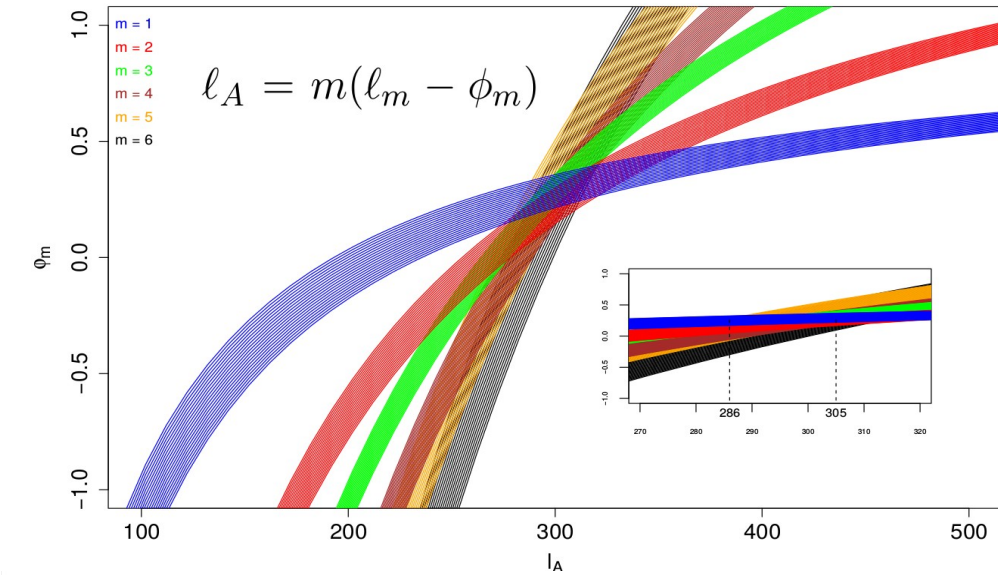


Picks and dips



(Aghamousa, Shafieloo, Arjunwadkar and Souradeep, JCAP, 2015)

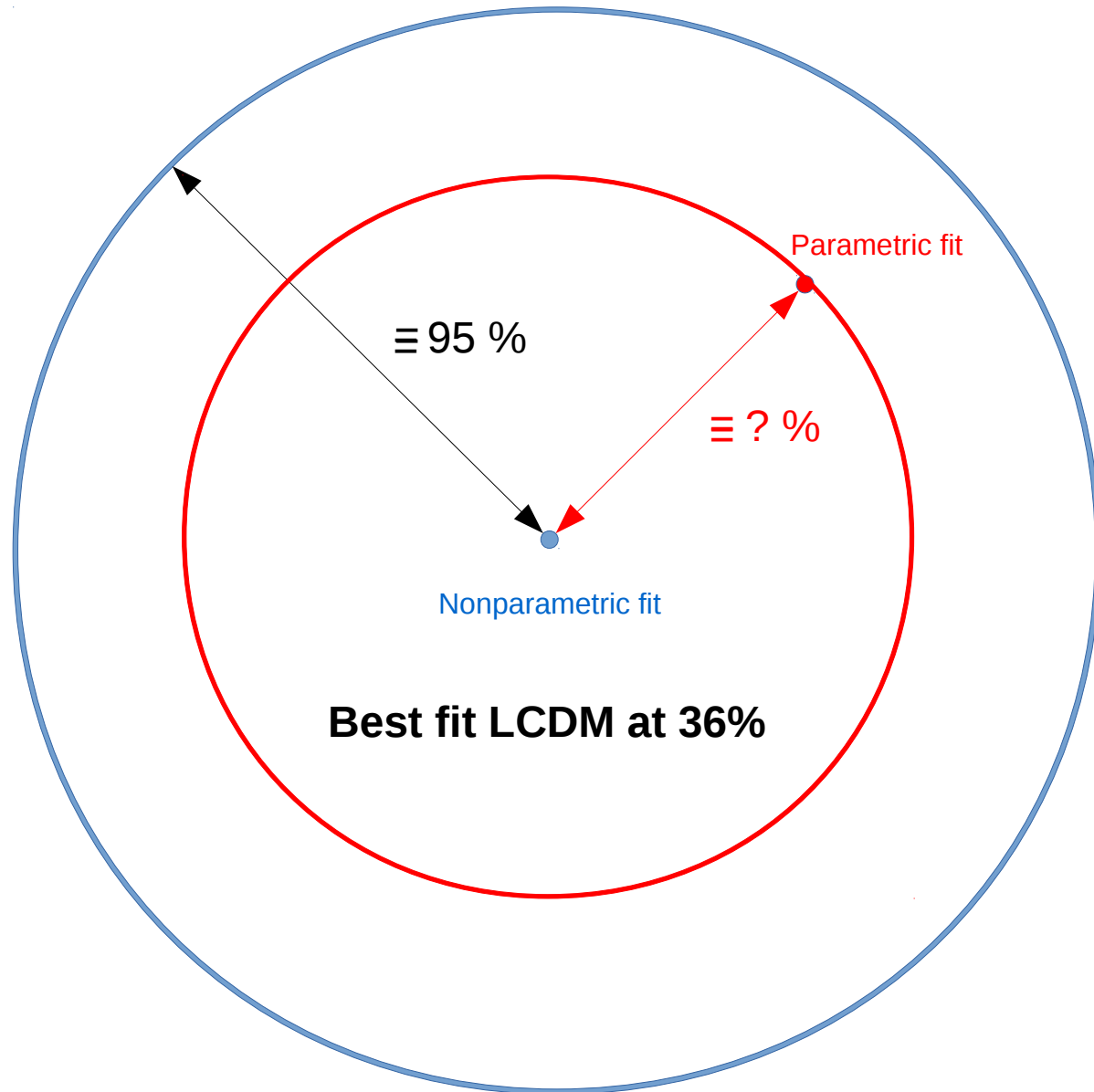
Other results



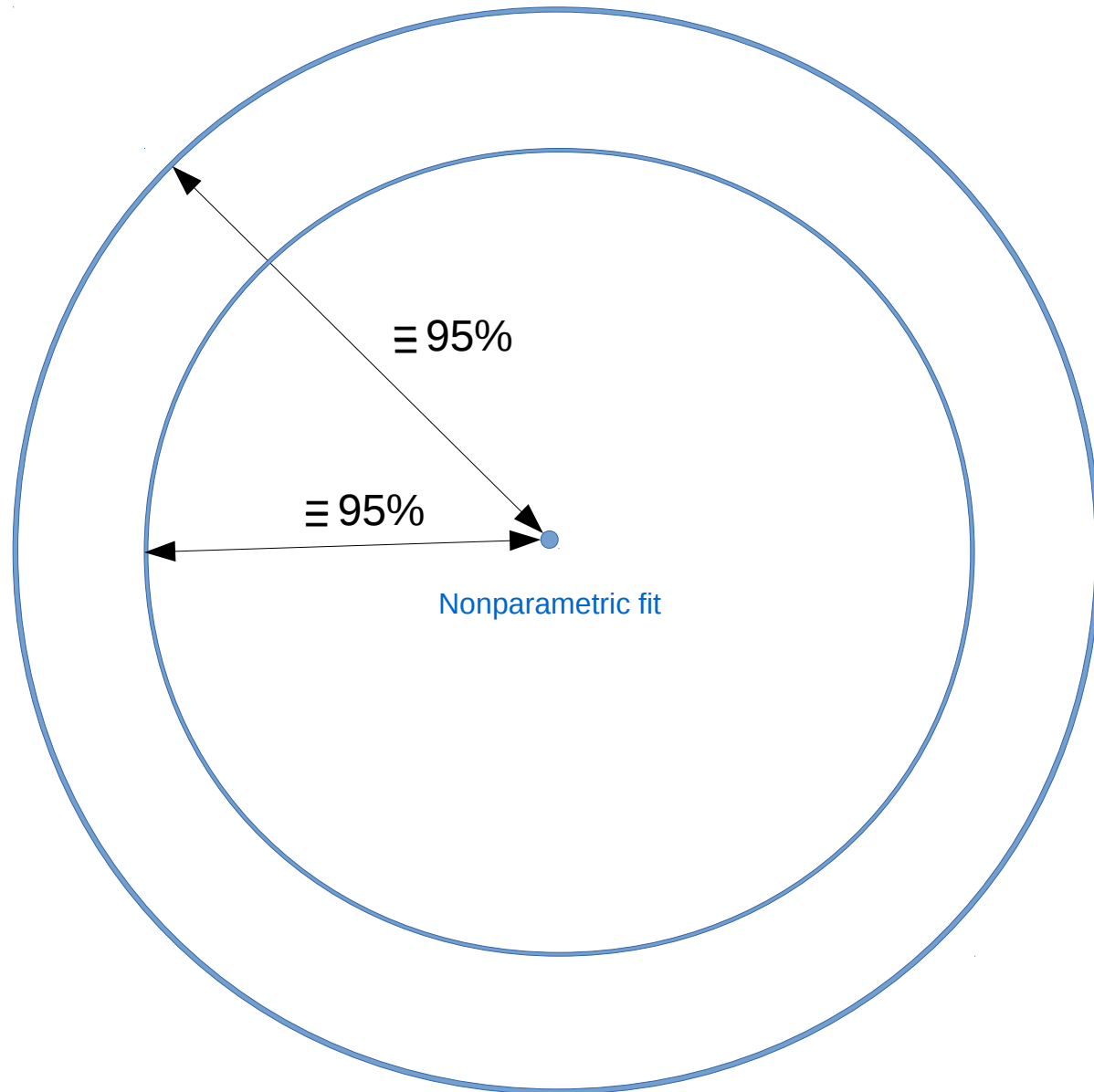
(Aghamoussa, Shafieloo, Arjunwadkar and Souradeep, JCAP, 2015)

Nonparametric test of consistency between cosmological models and CMB data

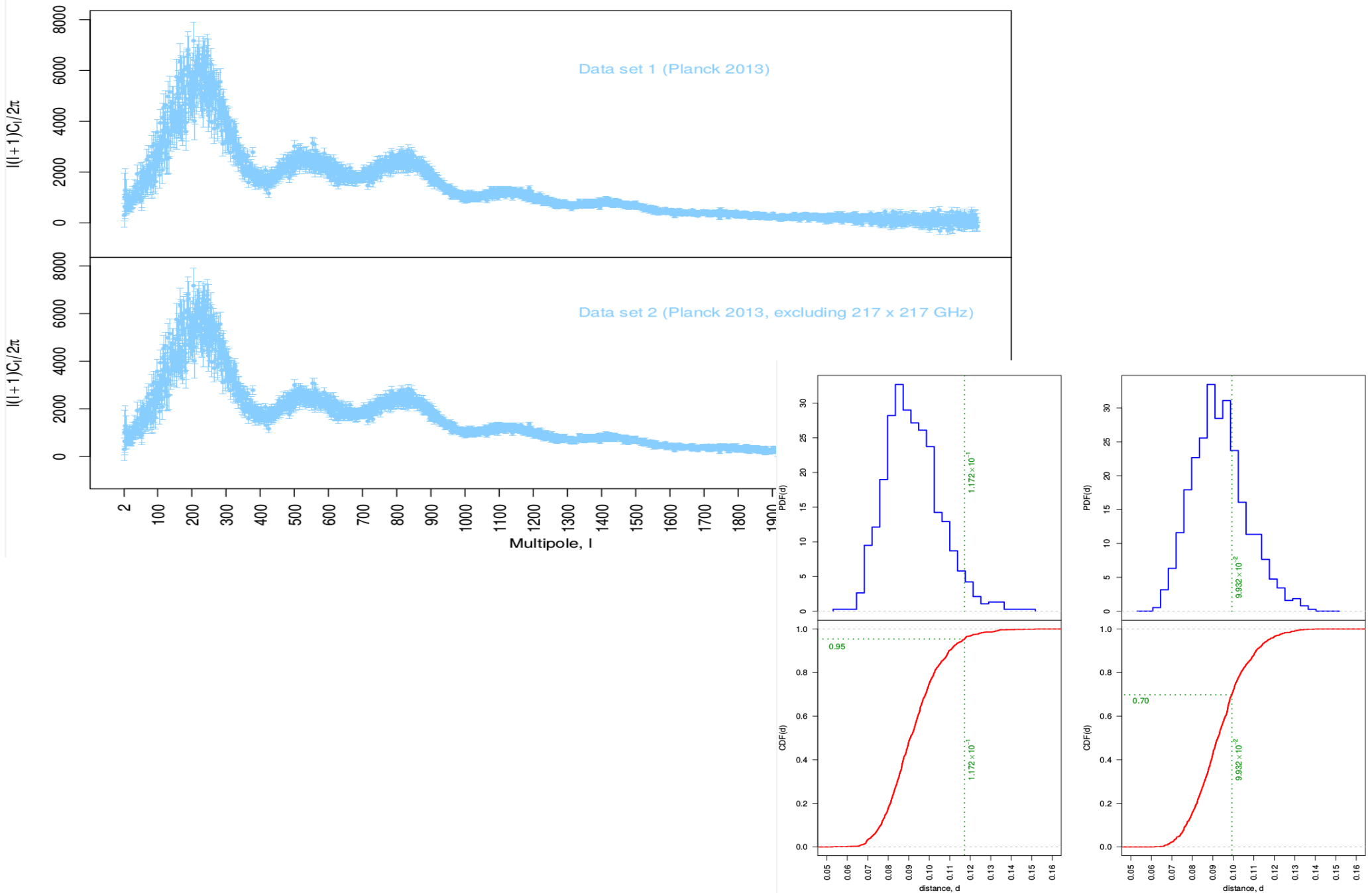
Validating Cosmological Models



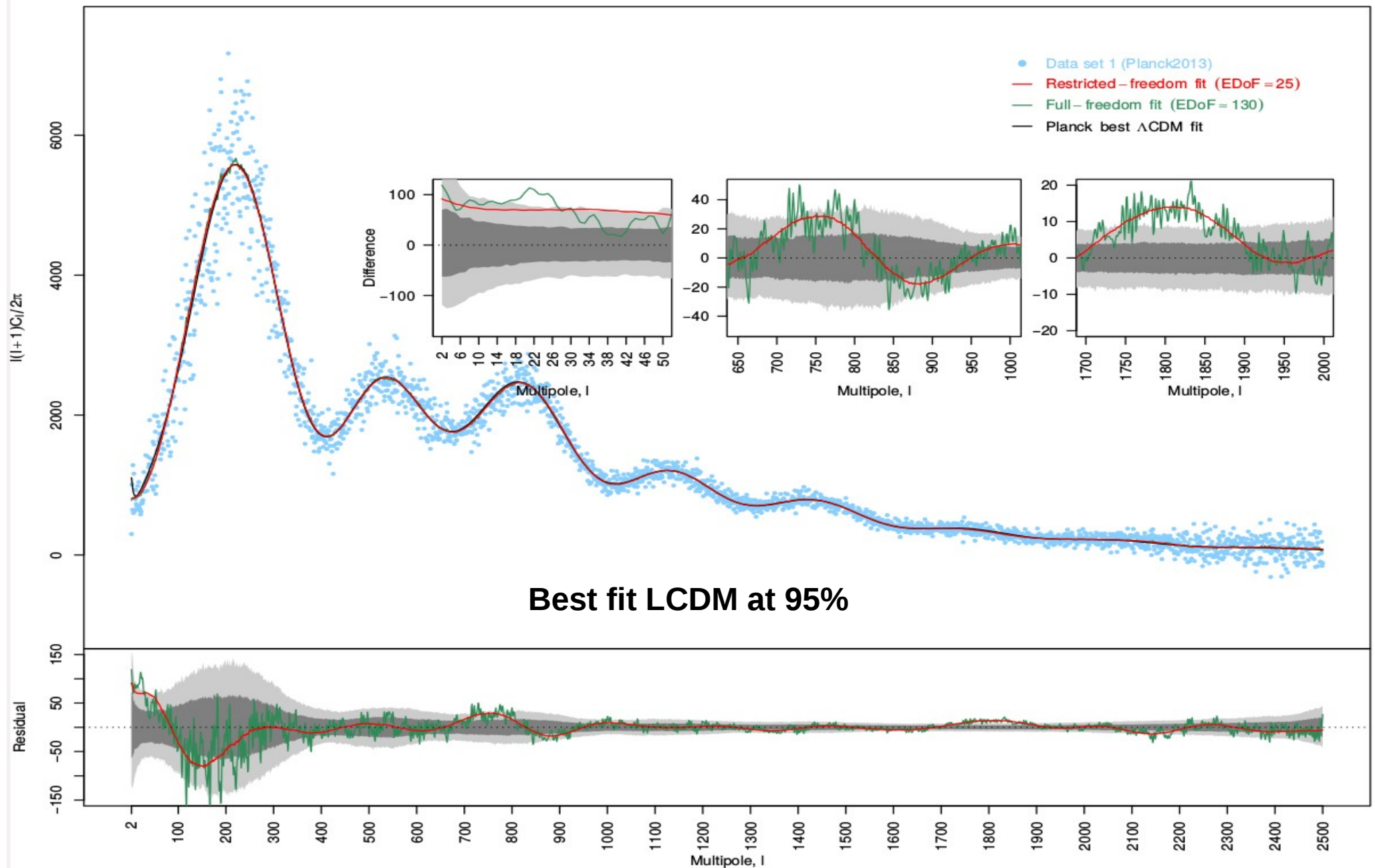
Calibrating Confidence distances



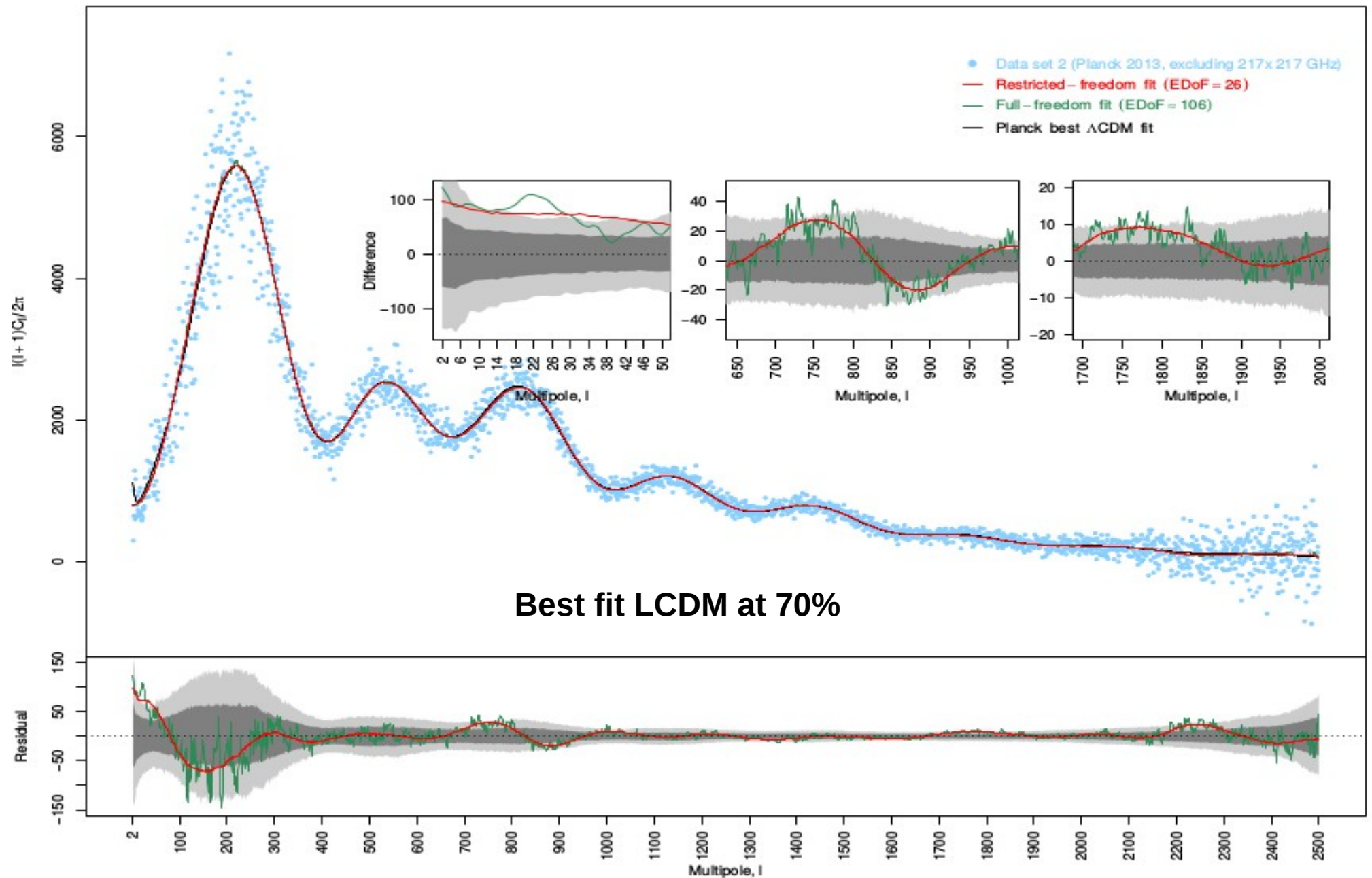
Calibrating Confidence distances



Bias control



Bias control



Conclusion

- Strong Lens Time Delay Challenge II: designing an algorithm for time delay estimation based on the smoothing and cross correlation.
- Time delay estimation of SDSS J1001+5027: Applying improved algorithm on real data. Using weighted correlation and number of data criterion.
- Supernova Type Ia classification: Using Gaussian process and 2-D Kernel density to find a unique pattern for supernova type Ia.
- Model-independent estimation of CMB angular power spectrum: estimation power spectrum, uncertainties of peaks and dips, harmonicity of peaks and a proper estimation of likelihood.
- Nonparametric test of consistency between cosmological models and CMB data: consistency check of Best LCDM power spectrum with Planck 2013 data with and without 217 channel data.
- Finally: using advanced statistics and modified techniques enable us to infer more accurate and robust results from the data.

