

# Phenomenology of Heterotic Compactifications with Torsion

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# Outline

## 1 Background: heterotic strings and torsion

- Moduli stabilization overview
- $SU(3)$  structure and half-flat manifolds
- Domain wall vacuum

## 2 $Spin(7)$ structures

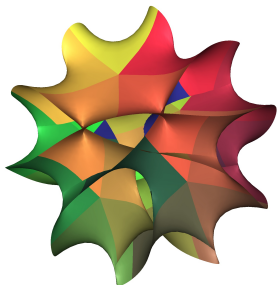
- $Spin(7)$  and generalized half-flat manifolds
- $10d$  flow equations and matching to  $4d$  1/4-BPS equations

## 3 Inflation

- Background: Anomalous  $U(1)$  symmetries
- Inflation: simple case
- Extension: two-axion model

# Calabi–Yau compactification

- Superstring theory is self-consistent only in 10 spacetime dimensions.
- Assume the extra 6 spatial dimensions are **compactified**.
- Lots of supersymmetry in  $d = 10$  → want to break most of it.
- Amount of broken SUSY  $\Rightarrow$  **holonomy group** of compactification manifold.
- Maximum holonomy is  $SO(6) \cong SU(4) \Rightarrow$  no SUSY preserved.
- **Calabi–Yau manifold**:  $SU(3)$  holonomy  $\Rightarrow$  1/4 SUSY preserved
  - e.g. heterotic Calabi-Yau: 4 of 16 supercharges unbroken.



## Problems with heterotic moduli stabilization

- In heterotic string theory, only have NS-NS flux  $H_3$ .
- Can stabilize complex structure moduli... then what?
- Dilaton can be stabilized by gaugino condensation.
- Limited options for remaining moduli (worldsheet instantons...)
- In fact, problem is even worse:

### Strominger, 1986

If a heterotic compactification on a manifold  $Y$  has a **maximally symmetric** (e.g. Poincaré) vacuum and non-vanishing  $H_3$ ,  $Y$  is non-Calabi–Yau.

- Hence for a Calabi–Yau compactification,  $H_3 = 0!$

# What is an SU(3) structure manifold?

- Mirror dual of  $H_3$ : manifold with SU(3) structure  
hep-th/0008142 (Vafa), hep-th/0211102 (Gurrieri *et al*).
- **SU(3) structure**: there is a globally-defined spinor  $\zeta$  that leaves 1/4 of the SUSY unbroken.
- Calabi–Yau case:  $\zeta$  is covariantly constant with respect to the Levi-Civita connection  $\nabla$ .
- Non-CY case:  $\nabla\zeta \sim T^0\zeta$  (note:  $\Gamma$  matrices/indices suppressed).
- $T^0$  is the **intrinsic torsion** of the manifold.
- SU(3) decomposition: torsion splits into 5 **torsion classes**,

$$T^0 \in \mathcal{W}_1 \oplus \mathcal{W}_2 \oplus \mathcal{W}_3 \oplus \mathcal{W}_4 \oplus \mathcal{W}_5 .$$

## Half-flat manifolds

Two (not mutually exclusive) ways to satisfy Strominger's theorem:

### Option 1:

Study compactifications on SU(3) structure manifolds with torsion.

- Has been studied in eg. hep-th/0408121 (Gurrieri, Lukas, Micu), hep-th/0507173 (de Carlos, Gurrieri, Lukas, Micu).
- Torsion quantization understood for **half-flat manifolds**.
- Expanding the SU(3) invariant forms on appropriate bases, the only non-closed basis forms in the half-flat case satisfy

$$d\omega_i = e_i \beta^0, \quad d\alpha_0 = e_i \tilde{\omega}^i.$$

- For half-flat manifolds, torsion falls into the SU(3) classes

$$T^0 \in \mathcal{W}_1^+ \oplus \mathcal{W}_2^+ \oplus \mathcal{W}_3,$$

where  $+$  denotes the real part of  $\mathcal{W}$ .

# Domain wall vacuum

## Option 2:

Break maximal symmetry of  $d = 4$  spacetime.

- Compactification with  $H$ -flux on a half-flat or Calabi-Yau manifold.
- There exist 1/2-BPS domain wall solutions 1305.0594 (Klaput, Lukas, Svanes).
- 1/2-BPS: 2 of the 4 SUSY generators in  $d = 4$ ,  $\mathcal{N} = 1$  unbroken.
- $d = (2 + 1)$  Poincaré symmetry preserved; DW breaks symmetry in transverse  $y$  direction.
- Moduli satisfy flow equations in the  $y$  coordinate.
- 10d perspective:  $SU(3)$  fibred over  $y \rightarrow G_2$  structure arXiv:1005.5302 (Lukas, Matti).

## Spin(7): two transverse coordinates

- The domain wall solution is a special case of the metric

$$ds_4^2 = e^{-2B(x_a)} \left( \eta_{\alpha\beta} d\tilde{x}^\alpha d\tilde{x}^\beta + g_{ab} dx^a dx^b \right) .$$

- We can consider more general codimension-2 topological defects.
- 10d perspective: looks like an 8-dimensional **Spin(7) structure**.
- For the corresponding 6d compact SU(3) structure manifold, consider a **generalized half-flat manifold**, which satisfies

$$d\omega_i = p_{Ai}\beta^A - q_i^A\alpha_A, \quad d\alpha_A = p_{Ai}\tilde{\omega}^i, \quad d\beta^A = q_i^A\tilde{\omega}^i, \quad d\tilde{\omega}^i = 0,$$

where  $\omega_i$  and  $(\alpha_A, \beta^B)$  are basis 2- and 3-forms, respectively.

- Relevant SU(3) torsion classes are now

$$T^0 \in \mathcal{W}_1 \oplus \mathcal{W}_2 \oplus \mathcal{W}_3 .$$



# Flow equations: ten-dimensional perspective

- **Ten-dimensional perspective:**  
6 compact dimensions + 2 non-compact directions  $x$  and  $y$   
→ **8d Spin(7) structure.**
- Killing spinor can be written in terms of invariant Cayley 4-form  $\Psi$ .
- Decompose  $\Psi$  under the 6d SU(3) structure as

$$\Psi = \text{Re}(dz \wedge \Omega) + \frac{1}{2} J \wedge J + \text{dvol}_2 \wedge J ,$$

where  $dz = dx + idy$ ,  $\text{dvol}_2 = dx \wedge dy$ .

- $J$  is a 6d Kähler (1,1)-form, and  $\Omega$  is a holomorphic (3,0)-form (for a Calabi–Yau they are harmonic,  $dJ = d\Omega = 0$ ).
- 10d supersymmetry transformations give the 8d flow equations,

$$*_8 \hat{H} = -e^{2\hat{\phi}} d_8(e^{-2\hat{\phi}} \Psi) , \quad 12d_8 \hat{\phi} = \Psi \lrcorner d_8 \Psi = - *_8 (\Psi \wedge *_8 d_8 \Psi) ,$$

where  $\hat{\phi}$  is the 10d dilaton and  $\hat{H}$  is the 10d NS-NS flux.

# Compactification

- Expand  $J$  and  $\Omega$  in terms of the basis forms:

$$J = v^i \omega_i, \quad \Omega = z^A \alpha_A - \mathcal{G}_A \beta^A.$$

- The NS-NS 2-form potential and 3-form flux can be expanded as

$$\hat{B} = B + b^i \omega_i, \quad \hat{H} = H + db^i \wedge \omega_i + b^i d\omega_i + H_{\text{flux}},$$

where we have introduced  $H_{\text{flux}} = \mu^A \alpha_A - \epsilon_A \beta^A$ .

- Moduli superfields, including 4d dilaton  $\phi$ :

$$S = a + ie^{-2\phi}, \quad T^i = b^i + iv^i, \quad Z^a \equiv z^a / z^0 = c^a + iw^a.$$

- Consider **H-flux only on the internal space**  $\Rightarrow a \sim b^i \sim \text{constant}$ .
- Under SU(3)-structure decomposition, flow equations reduce to:

$$dJ = 2\text{Im} \left( \partial_{\bar{z}} \Omega - 2\partial_{\bar{z}} \hat{\phi} \Omega \right) - * \hat{H};$$

$$d\Omega = \partial_z (J \wedge J) - 2\partial_z \hat{\phi} J \wedge J; \quad \Omega \wedge \hat{H} = 4i * \partial_z \hat{\phi}.$$

## Four-dimensional perspective

- Let us also consider an ansatz for the 4d theory.
- Unbroken supercharge in singlet of  $Spin(7) \Rightarrow$  **1/4-BPS in 4d**.
- 1/4-BPS ansatz:  $\bar{\zeta} = \sigma^2 \zeta = i\sigma^3 \zeta$  gives Killing spinor equations

$$(\partial_x + i\partial_y) A^I = -ie^{-B} e^{K/2} K^{IJ*} D_{J*} W^* ,$$

$$(\partial_x + i\partial_y) B = -ie^{-B} e^{K/2} W^* ,$$

$$0 = \text{Im}(K_I \partial_a A^I) ,$$

$$2\partial_a \zeta = -\partial_a B \zeta ,$$

where  $a \subset \{x, y\} \equiv \{2, 3\}$ , and  $A^I = (S, T^i, Z^a)$ .

- GVW superpotential (for generalized half-flat manifolds):

$$W = \sqrt{8} \int \Omega \wedge (\hat{H} + idJ) = \sqrt{8} (\tilde{\mu}^A \mathcal{G}_A - \tilde{\epsilon}_A \mathcal{Z}^A) ,$$

with modified flux parameters  $\tilde{\epsilon}_A \equiv \epsilon_A - T^i \rho_{Ai}$ ,  $\tilde{\mu}^A \equiv \mu^A - T^i q_i^A$ .

## Matching the 10d and 4d equations

- Consistency: need to **match** the 10d flow equations to the 4d 1/4-BPS Killing spinor equations 1512.02812 (SA, Matti, Svanes).

### Summary of key points:

- 4d dilaton equation  $\Rightarrow$  warp factor  $B = \phi$  (up to a constant).
- $d\Omega$  equation in 10d  $\rightarrow$  KSE in 4d for the Kahler moduli  $T^i$ .
- $dJ$  equation in 10d  $\rightarrow$  KSE for complex structure moduli  $Z^a$ .
- $dJ \wedge \bar{\Omega}$  with  $\Omega \wedge \hat{H} \rightarrow$  dilaton equation,  $2\partial_{\bar{z}}\phi = -ie^{-\phi}e^{K/2}W^*$ , **BUT** only if we also impose the additional 10d constraint

$$\int \partial_z \Omega \wedge \bar{\Omega} = \int \Omega \wedge \partial_z \bar{\Omega}.$$

- Actually,  $\partial_z \Omega = K_z \Omega + \chi_z^{(2,1)}$ ; we are free to choose  $K_z$  real.
- Reducing this constraint to 4d  $\rightarrow$  axion constraint,  $K_a \partial_z c^a = 0$ .

# Summary I

- String compactifications generate moduli, which must be stabilized. This can be done using fluxes.
- For the heterotic string, only  $H_3$  present. One can compactify on  $SU(3)$  structure manifolds which are not Calabi–Yau, and/or sacrifice maximal symmetry in  $d = 4$ . Domain wall solutions have been studied.
- We considered the more general codimension-2 case: from a  $Spin(7)$  ansatz compactified on generalized half-flat manifolds, the flow equations correspond to 1/4-BPS solutions in  $4d$ .

## Outlook:

- Still need to find explicit solutions... possible connection to  $Spin(7)$  compactifications of F-theory? 1307.5858 (Bonetti, Grimm, Pugh)  
⇒ **Work in progress!**

# Moduli stabilization with aligned D-terms: a review

- Consider a half-flat manifold with axio-dilaton  $S = s + i\sigma$  and two Kähler moduli,  $T = t + i\tau$  and  $U = u + i\nu$ .
- Assume complex structure moduli absent, or stabilized already.
- Allow geometric flux on the 2-cycle  $t$  only, giving a perturbative superpotential

$$W_P = w + e_1 T ,$$

where  $T = t + i\tau$ . (NOTE: phenomenology conventions!)

- Here  $w$  is generated by either NS flux or  $\alpha'$  corrections.
- Assume an **anomalous  $U(1)$  symmetry** under which **only  $S$  and  $U$  transform**, giving D-terms of the form  $D = b/s + c/u$  ( $b, c$  real).
- Resulting scalar potential stabilizes all moduli, minimum is non-supersymmetric AdS. 1504.06978 (Lukas, Lalak, Svanes)

# Inflation: simple case

- A successful model of inflation must:
  - allow a **de Sitter phase**,  $V > 0$ ;
  - satisfy the **slow-roll conditions**,  $\epsilon, |\eta| \ll 1$ .
- Need to identify a flat direction for the inflaton field.
- Promising candidates: two axions ( $\sigma$  and  $\nu$ ) remain unstabilized.
- One linear combination is gauge-dependent; it will be absorbed by the  $U(1)$  gauge boson via the Stueckelberg mechanism.
- Lift the remaining gauge-invariant axionic direction with a **non-perturbative term**,

$$W_{\text{NP}} = Ae^{-\alpha(S-\beta U)},$$

which can arise from gaugino condensation in the hidden sector.

- We expect such models to have a Kähler potential of the form

$$K = -\ln s - \ln \kappa, \quad \kappa = \kappa_{ijk} t^i t^j t^k$$

where  $d_{ijk}$  are intersection numbers on the mirror manifold.

- In the particular model above, we choose  $\kappa = t^2 u$  in order to stabilize all moduli perturbatively.
- The final vacuum is **non-supersymmetric AdS**, so need to uplift: assume this can be done such that  $V_{\text{final}} = 0$ .
- Resulting potential has a **natural inflation** form

$$V = V_0 \left( 1 - \cos \left( \frac{\hat{\theta}}{f} \right) \right),$$

where  $\hat{\theta}$  is canonically normalized and the axion decay constant

$$f = \frac{1}{\alpha \sqrt{2(1 + \beta^2)}}.$$



## Two-axion model

- Natural inflation with a single axion field requires a **trans-Planckian field excursion** to match observations.
- Furthermore we did not explicitly achieve **de Sitter uplifting**.

How to address these issues?

- First consider adding an **additional Kähler modulus**,  $X = x + i\xi$ .
- Stabilize  $\xi$  with a worldsheet instanton superpotential,

$$W_{\text{NP2}} = B e^{-n_1 U - n_2 X},$$

which is gauge-invariant by construction.

- Second, choose a Kähler potential of the form  $\kappa = txu$ .
- With this choice, the **geometric flux induces vanishing of the tree-level potential** (at the cost of stabilizing moduli perturbatively).

- The leading contributions to the scalar potential are

$$V = \frac{1}{s} \left[ \frac{b}{s} + \frac{c}{u} + \frac{d}{x} \right]^2 + \frac{1}{stux} \left\{ (w - e_1 t)^2 + e_1^2 \tau^2 \right. \\ \left. - 2|A|e^{-\hat{S}} \left[ (w - e_1 t + 2\hat{S}(w + e_1 t)) \cos \hat{\sigma} - (1 + 2\hat{S})e_1 \tau \sin \hat{\sigma} \right] \right. \\ \left. - 2|B|e^{-\hat{X}} \left[ (w - e_1 t + 2\hat{X}(w + e_1 t)) \cos \hat{\xi} - (1 + 2\hat{X})e_1 \tau \sin \hat{\xi} \right] \right\},$$

where  $\hat{S} = \alpha(S - \beta U)$  and  $\hat{X} = n_1 U + n_2 X$  are gauge-invariant.

- To leading order, the components of  $T$  are stabilized at

$$t \simeq \frac{w}{e_1}, \quad \tau \simeq 0.$$

- Subleading corrections give even further subleading terms in the scalar potential, which we can neglect for now.

- For the D-term potential to be minimized, we find that

$$\frac{1}{s} \left[ \frac{b}{s} + \frac{c}{u} + \frac{d}{x} \right]^2 = \frac{8e_1}{sxu} \left[ \frac{|A|\hat{s}(\hat{s}+2)e^{-\hat{s}}}{3} + \frac{|B|\hat{x}(\hat{x}+2)e^{-\hat{x}}}{3} \right].$$

- Hence the remaining inflation potential takes the form

$$V = \frac{8e_1}{sxu} \left[ |A|\hat{s}e^{-\hat{s}} \left( \frac{\hat{s}+2}{3} - \cos \hat{\sigma} \right) + |B|\hat{x}e^{-\hat{x}} \left( \frac{\hat{x}+2}{3} - \cos \hat{\xi} \right) \right].$$

- Supergravity approximation:  $\hat{s}, \hat{x} \gtrsim 1 \Rightarrow$  **de Sitter!**
- For  $n_1 \gg n_2$  and  $\beta \gg 1$ , the axions are almost aligned along the  $\nu$  direction  $\rightarrow$  variation of **aligned natural inflation** possible.  
hep-ph/0409138 (Kim, Nilles, Peloso)
- However, recall that this violates the Weak Gravity Conjecture applied to axions/instantons.
- Also, to completely stabilize  $s$  and  $x$ , need  $g_s$  and  $\alpha'$  corrections.

# Summary II

- Using aligned D-terms all moduli can be stabilized, leaving only massless axions. Resulting vacuum is non-supersymmetric AdS.
- Including non-perturbative contributions from gaugino condensation and worldsheet instantons, natural inflation can be realized eg. 1409.8436 (Abe, Kobayashi, Otsuka).
- With two light axions, aligned natural inflation is possible; de Sitter uplifting can be achieved by geometric flux and D-terms.
- However, some moduli become destabilized — saved by quantum corrections?